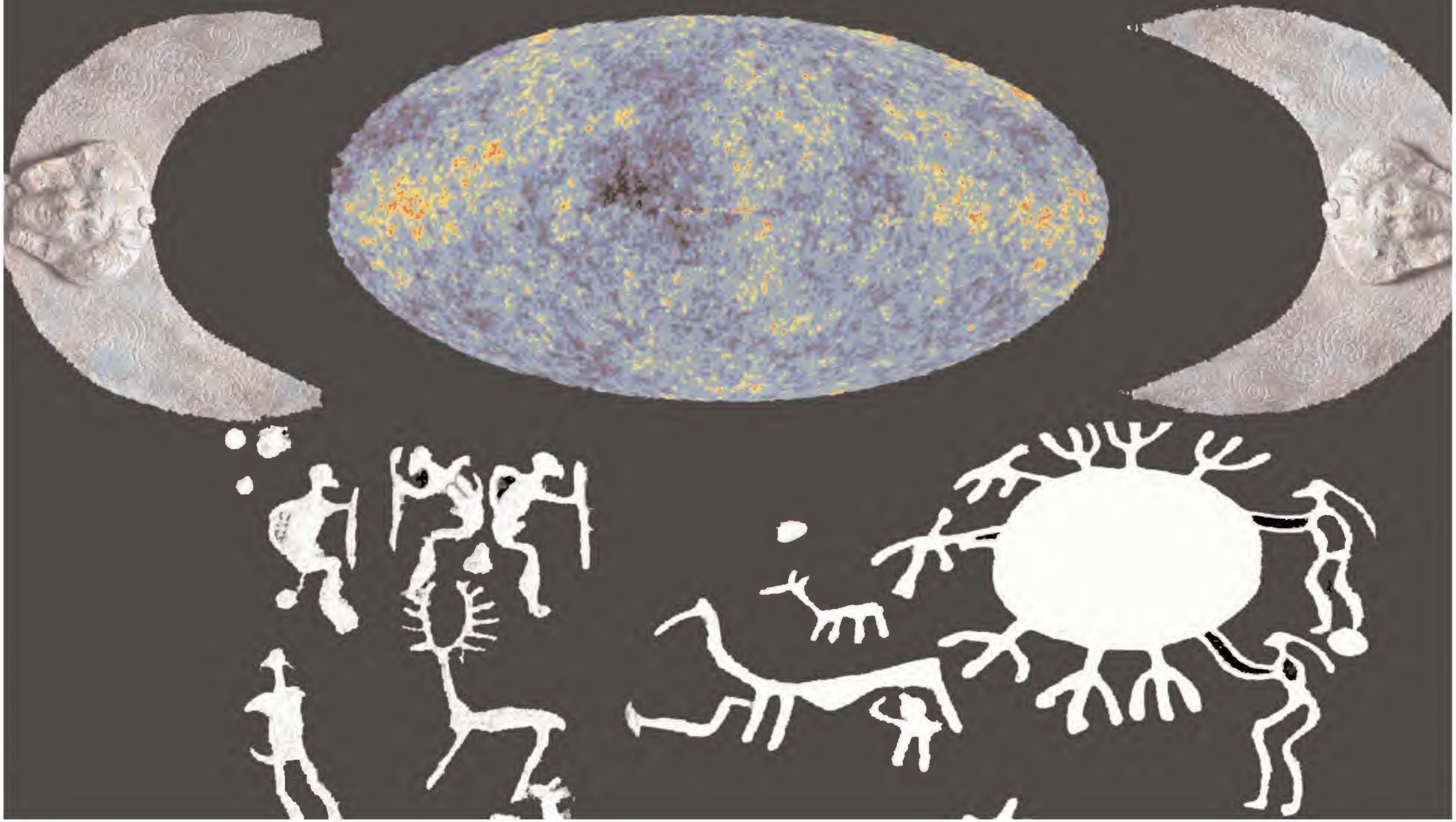
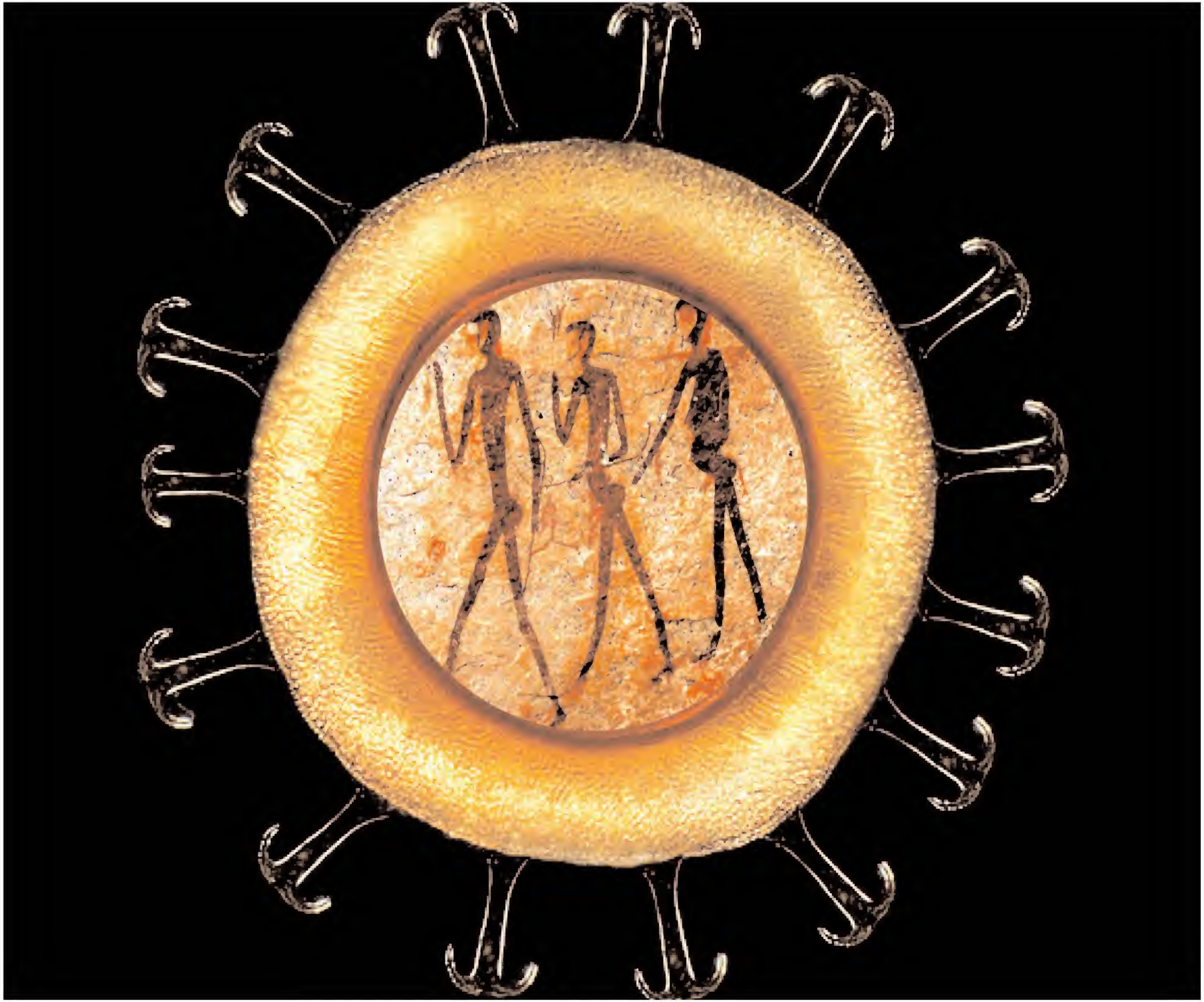
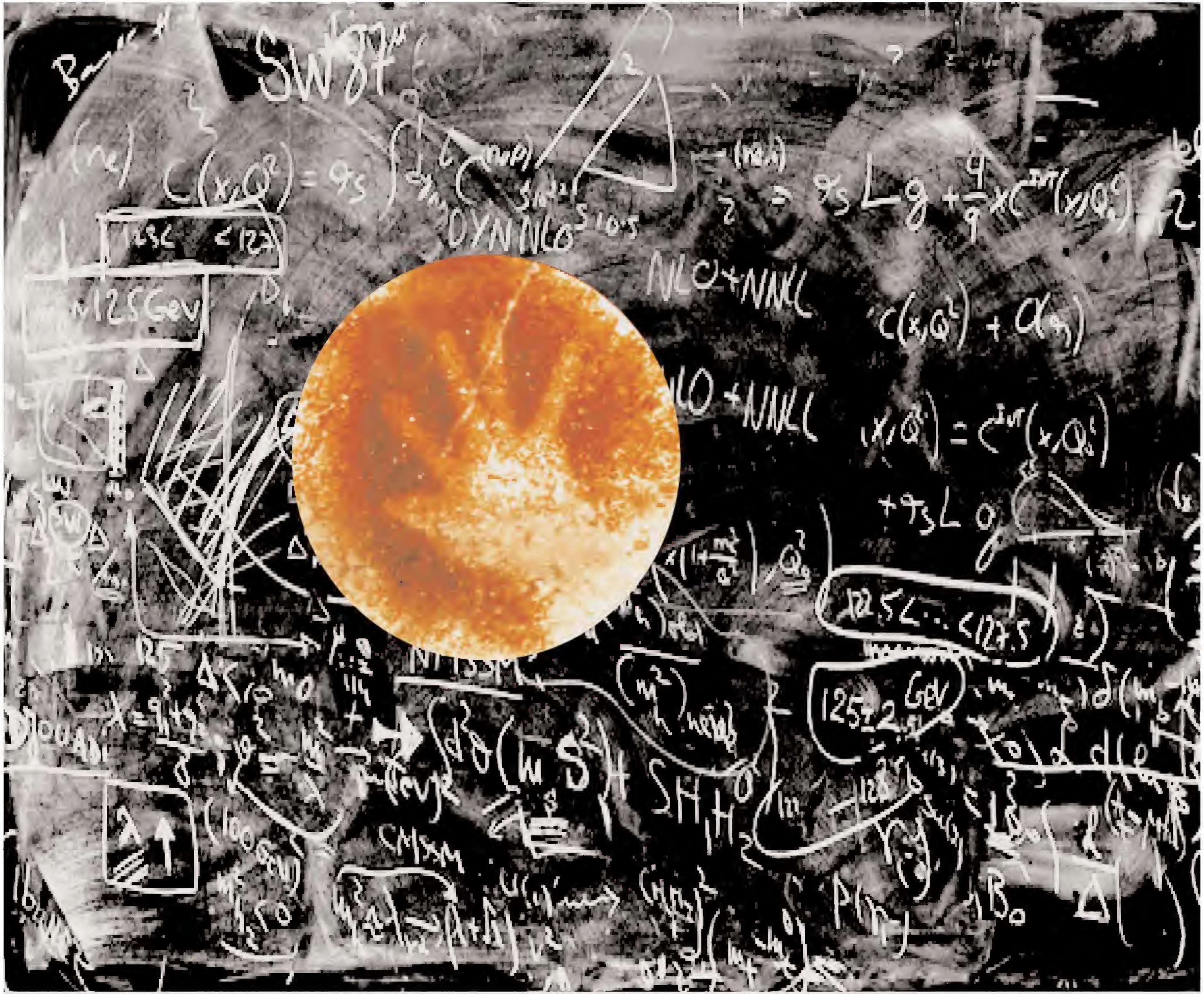
LA GROTTE DU PRIMITF QUANTIQUE

CLAUDE PAQUET

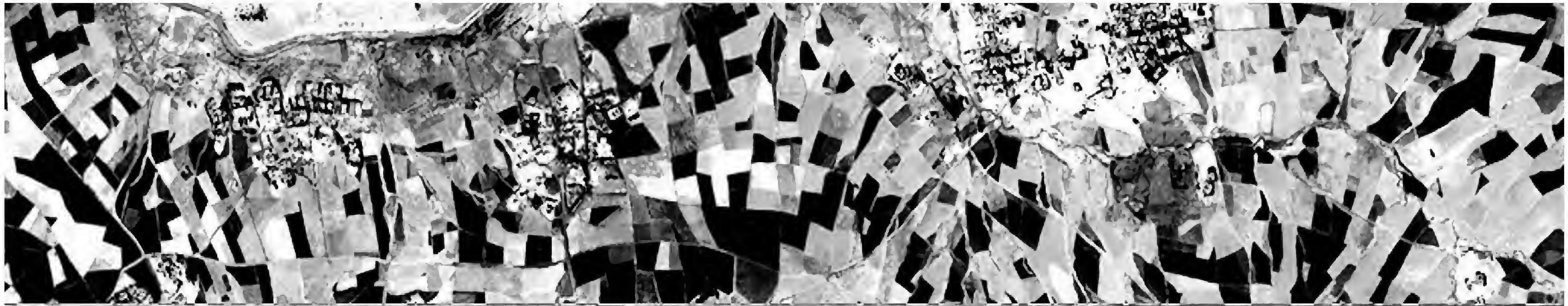


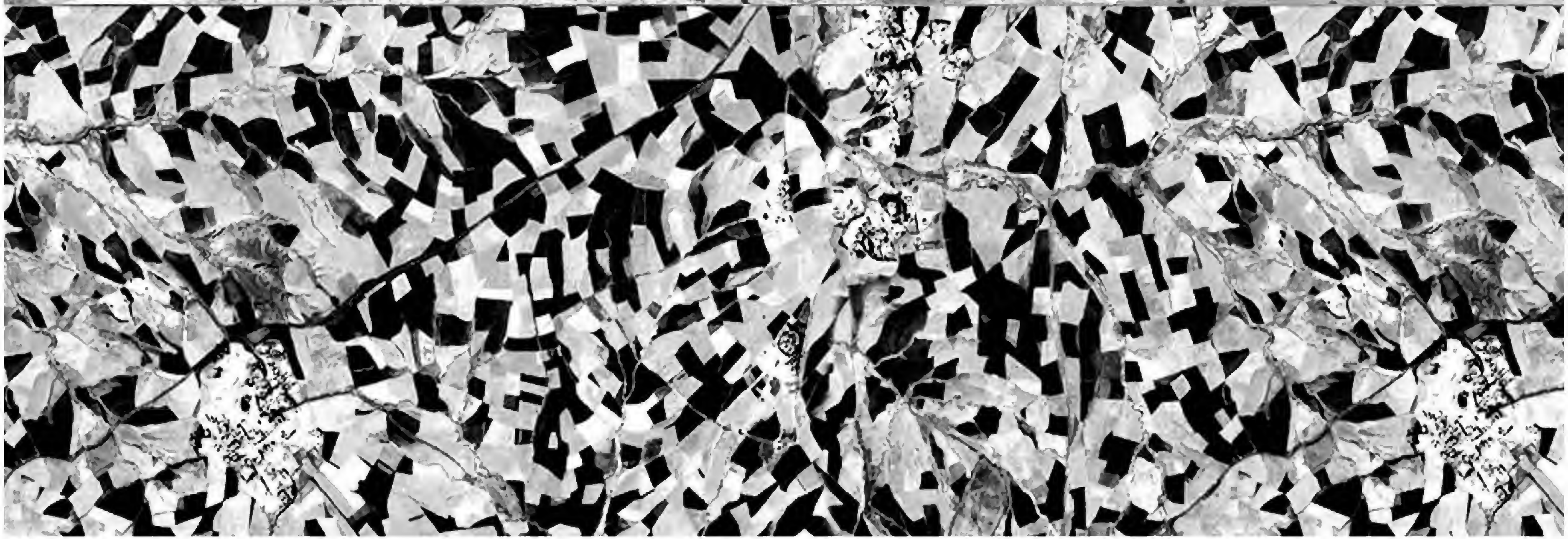




SW87
DYNNLO
NLO+NNLL
NLO+NNLL
125 GeV
125±2 GeV
CMSSM

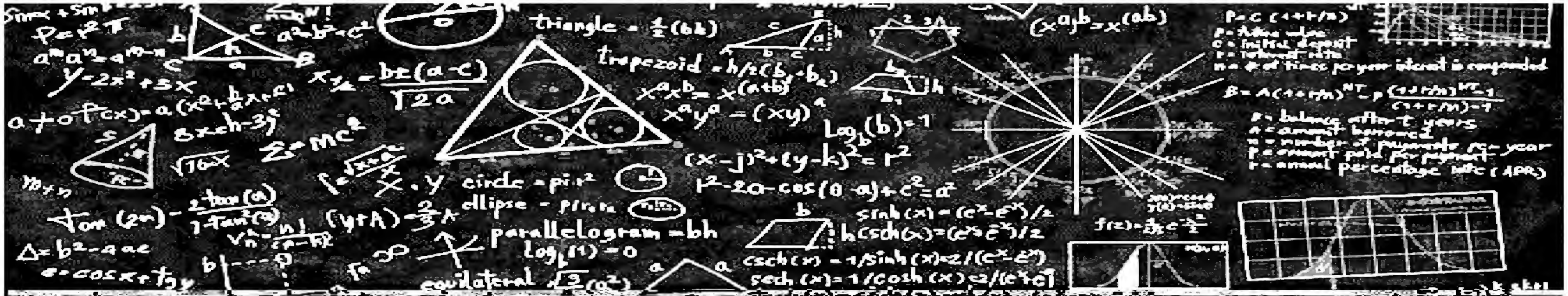
NNLO

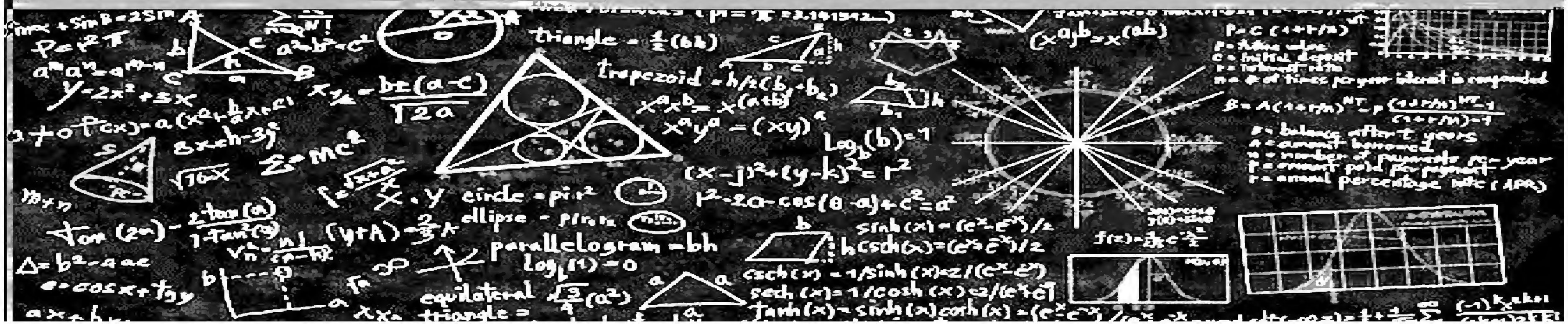





$(a+b)^2=a^2+2ab+b^2$
square $= a^2$
rectangle $= ab$
$a^2-b^2=(a+b)(a-b)$
Area Formulas
triangle $= \frac{1}{2}(bh)$
trapezoid
$(x^a)^b=x^{(ab)}$
$y=2x^2+3x$
H_2O
CO_2


E = V2/P3 + 4P
E=mc2
3b+(-2P/cos) = 6(2b)
f(x) = 2-x+1, ε=0,005
α,β,γ∈C


triangle = ½ (bh)
trapezoid = h/2 (b₁+b₂)
circle = pi r²
ellipse
parallelogram = bh
equilateral
E = mc²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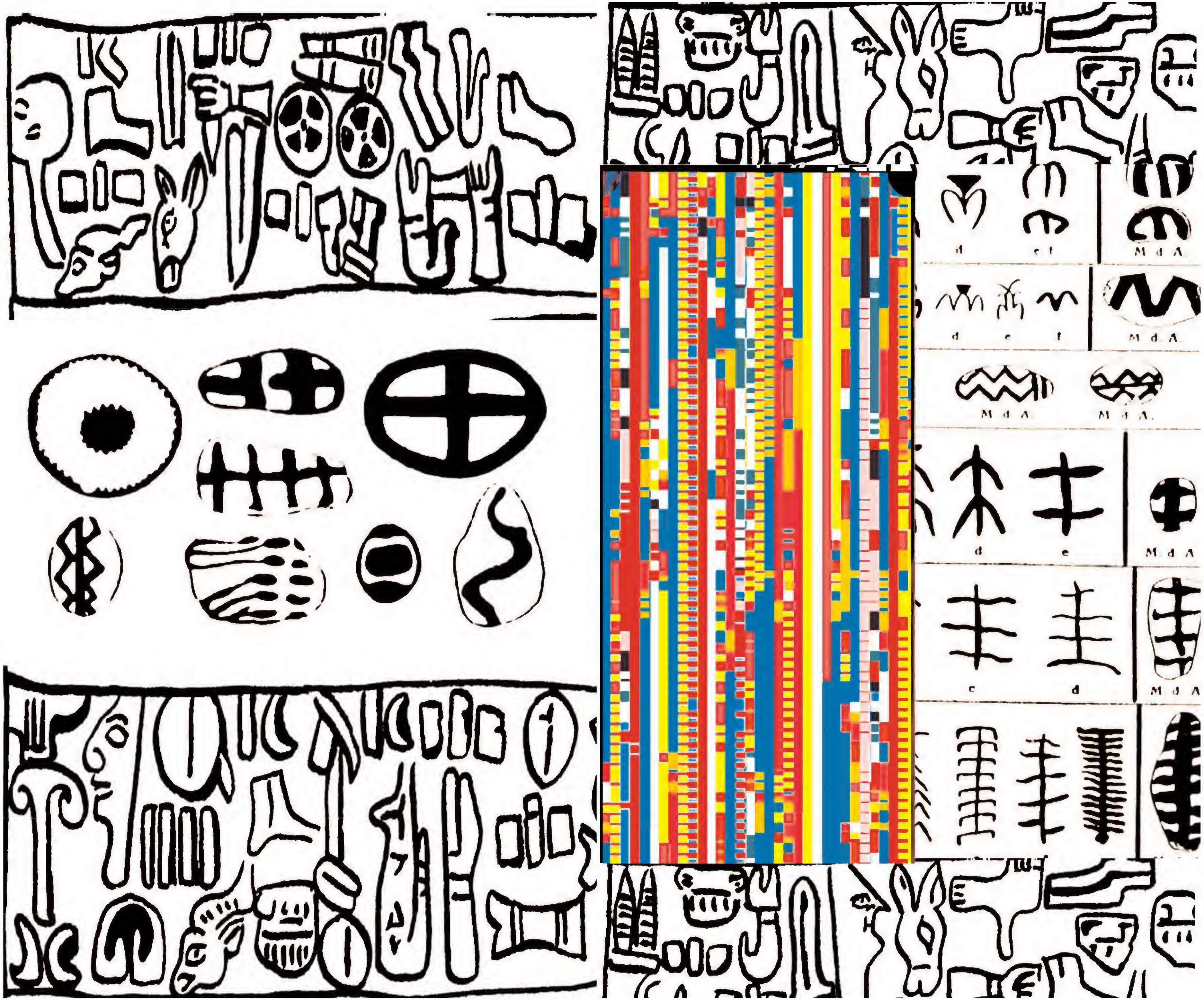
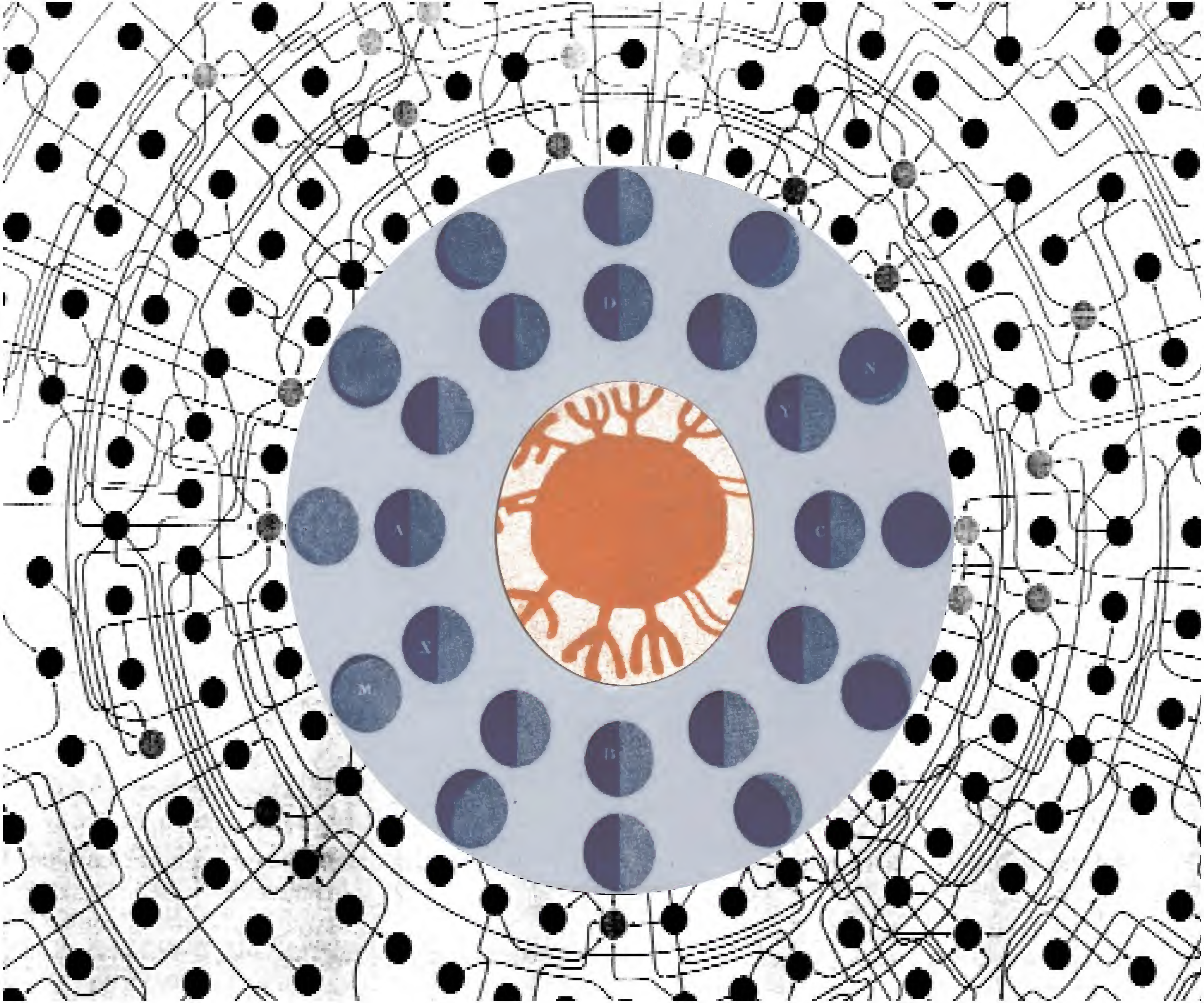

d
e f
M d A.
d e f
M d A.
M d A.
M d A.
d
e
M d A.
c
d
M d A.


D
N
Y
A
C
X
M.
B

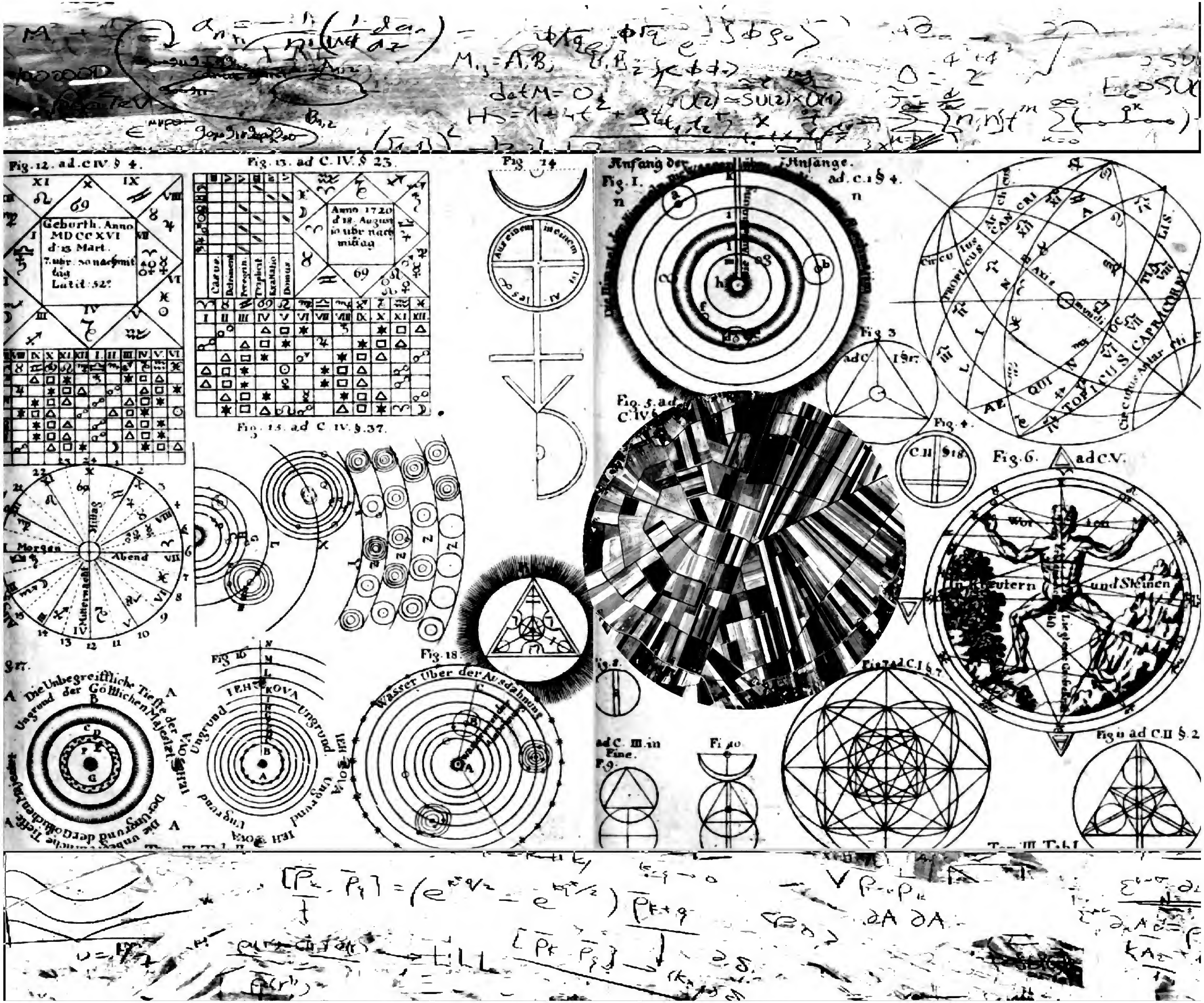
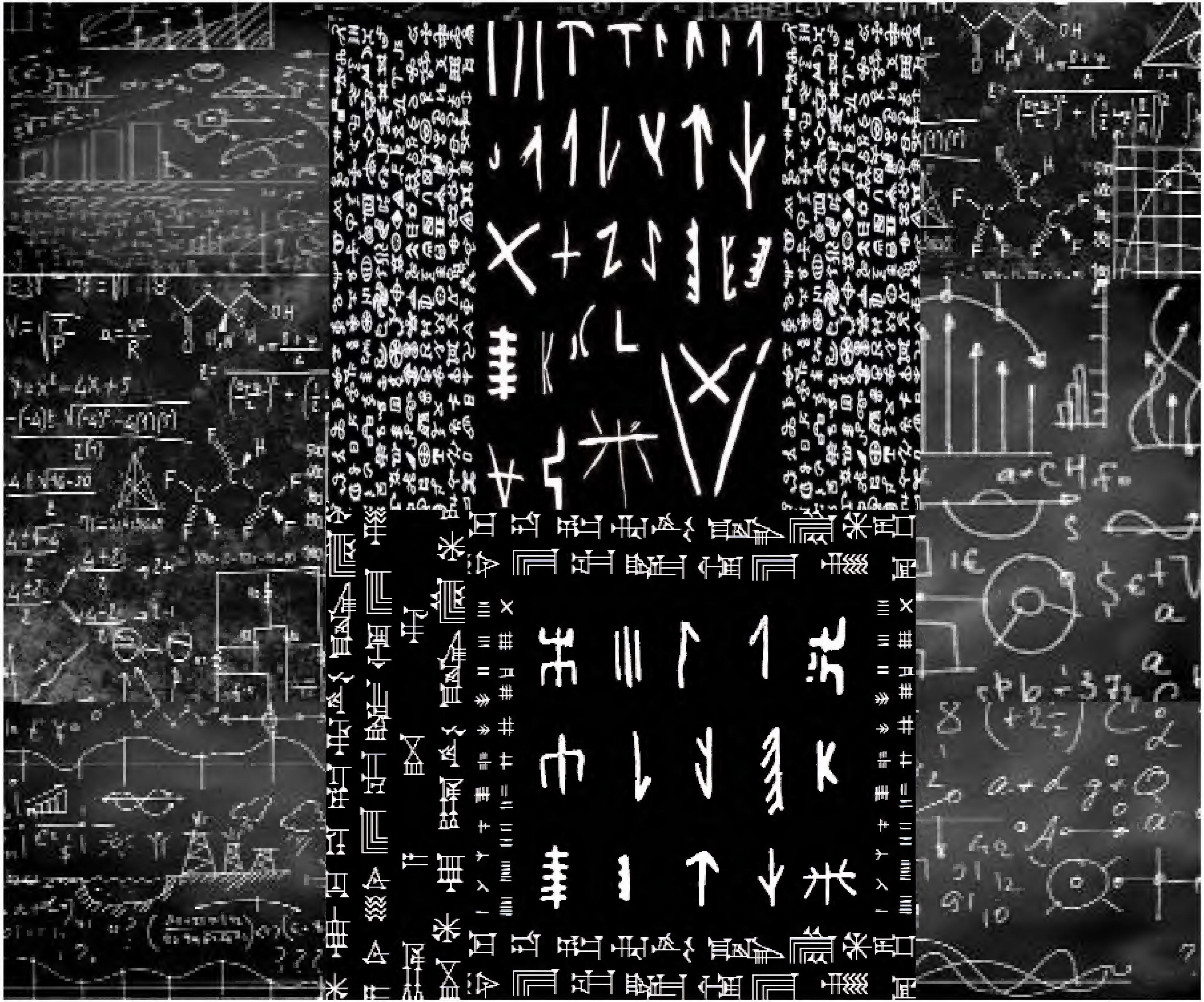
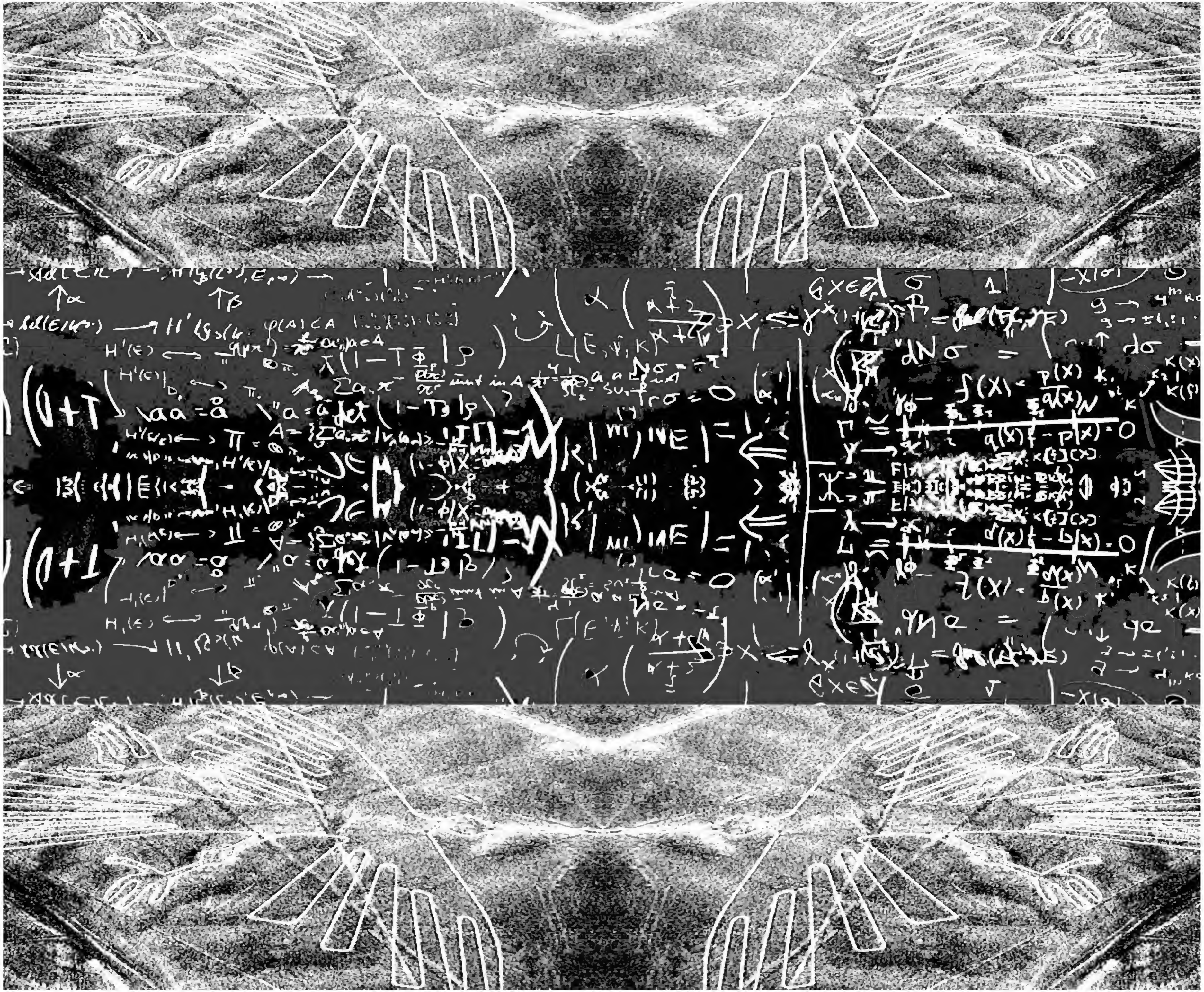
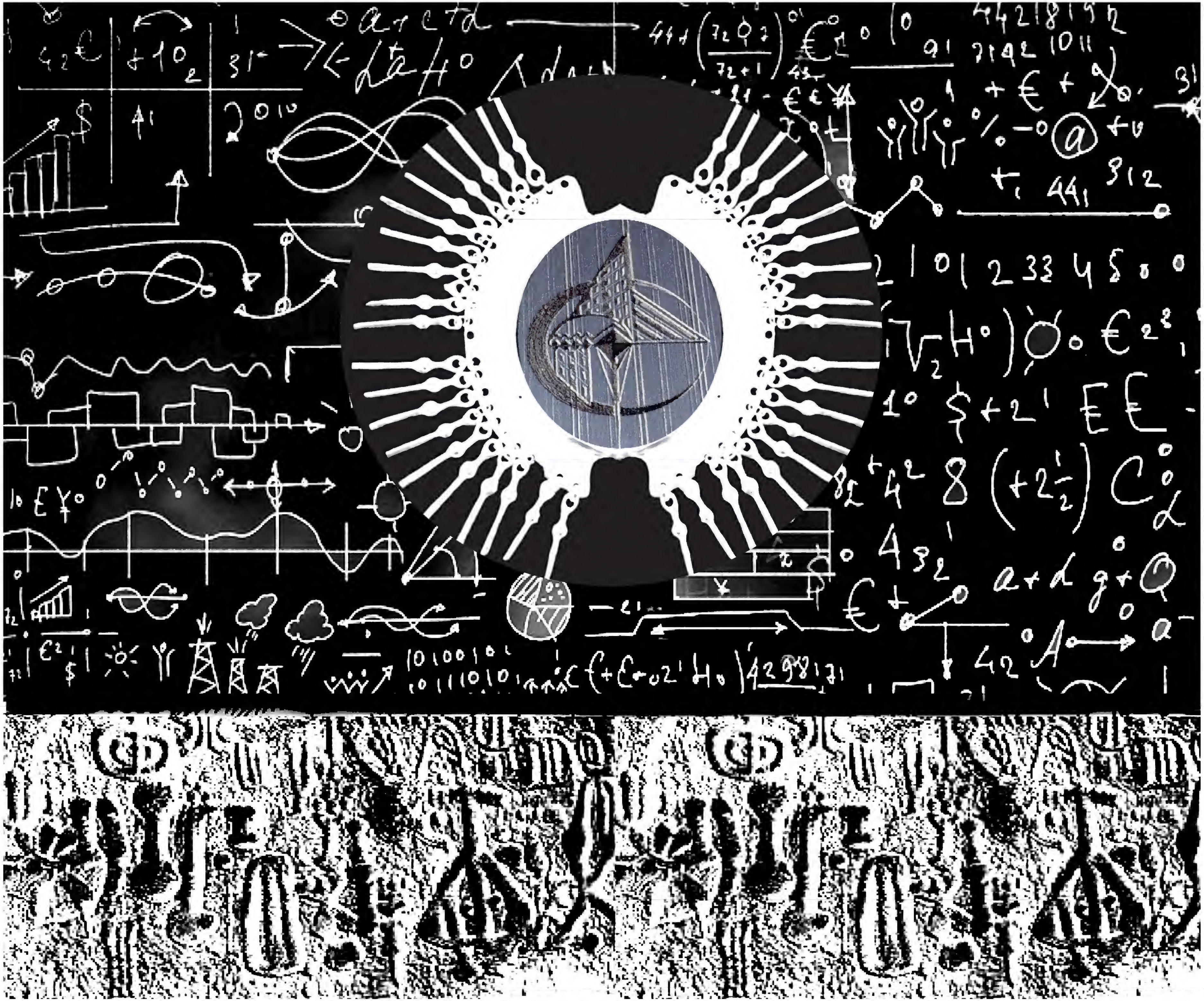
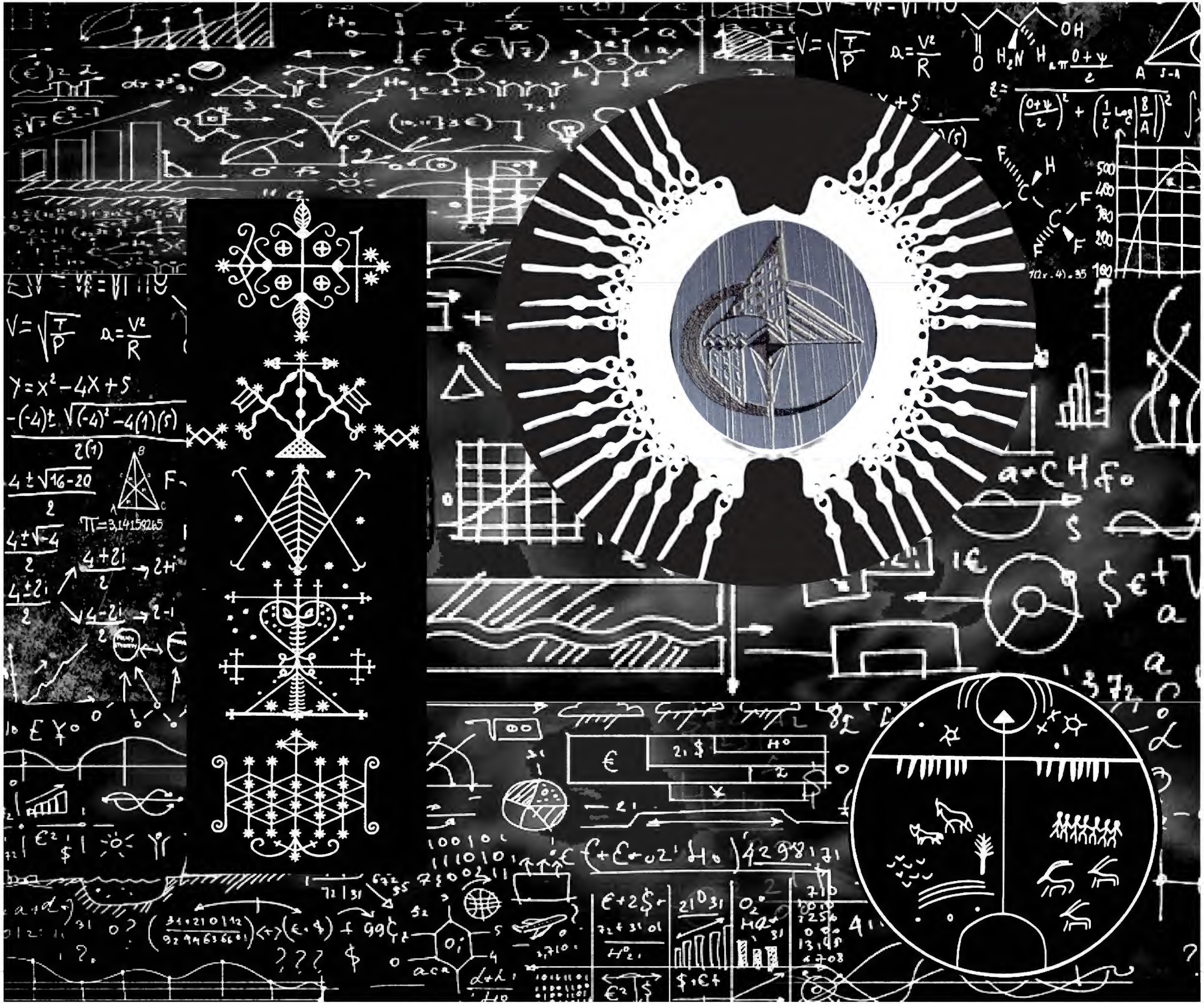


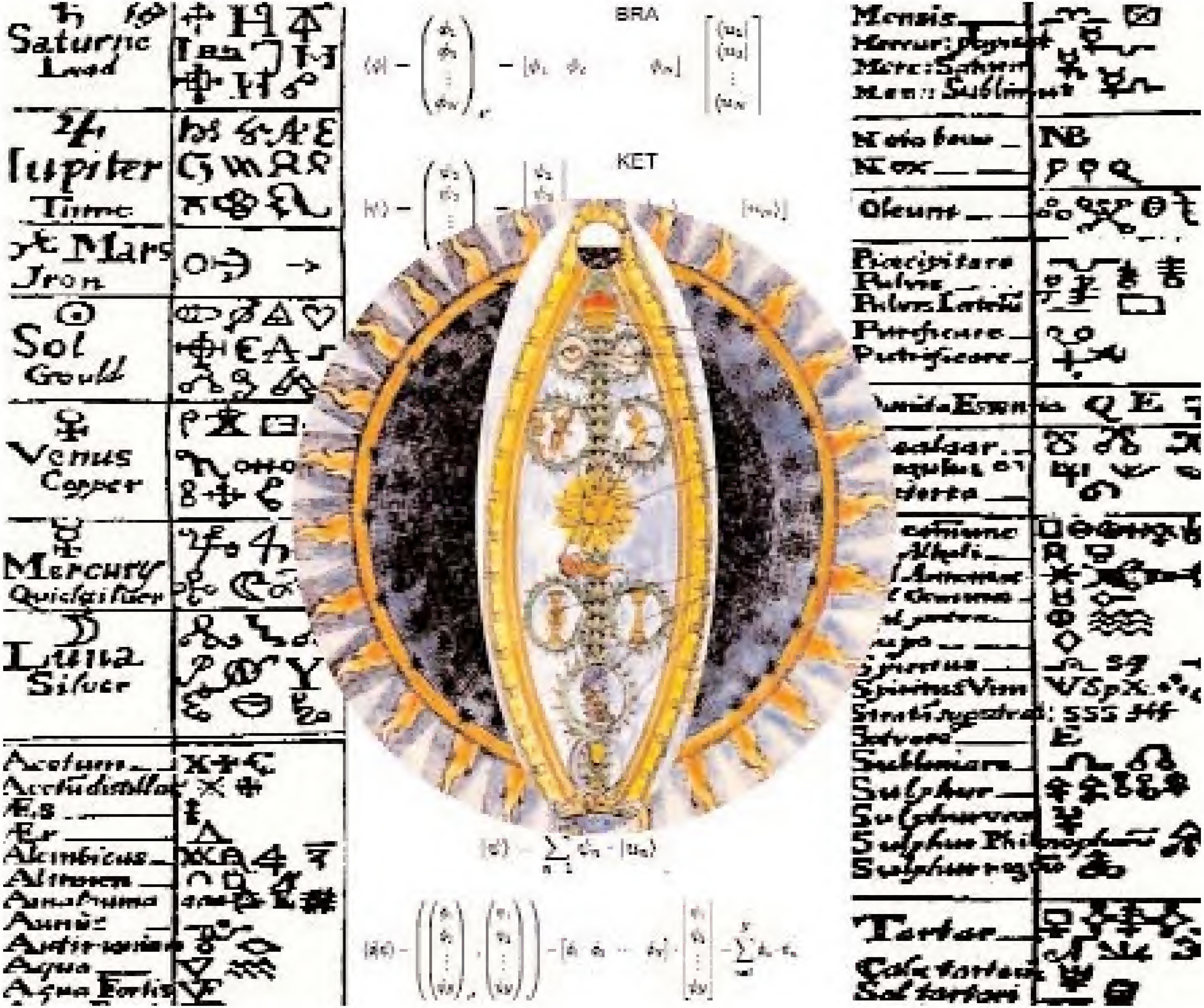
Fig. 12. ad. C. IV. § 4.
Geburth Anno MDCCXVI d 13 Mart.
Latit: 52°
Fig. 13. ad C. IV. § 23.
Anno 1720 d 18. Augusti 10 uhr nach mittag
Fig. 15. ad C. IV. § 37.
Morgen
Abend
Mittag
Mitternacht
Fig 14
Fig. 18.
Wasser über der Ausdehnung
Die Unbegreiffliche Tieffe der Ungrund der Göttlichen Majestät
IEHOVA
Ungrund
Anfang der Anfänge.
Fig. I.
ad. C. I § 4.
Fig 3
Fig. 4.
C. II § 18
Fig. 6.
ad C.V.
in Kreutern
und Steinen
TROPICUS CAPRICORNI
Fig 11 ad C. II § 2
ad C. III. in Fine.
Fig. 9.
Fig 10
det M = 0
SU(2) × U(1)



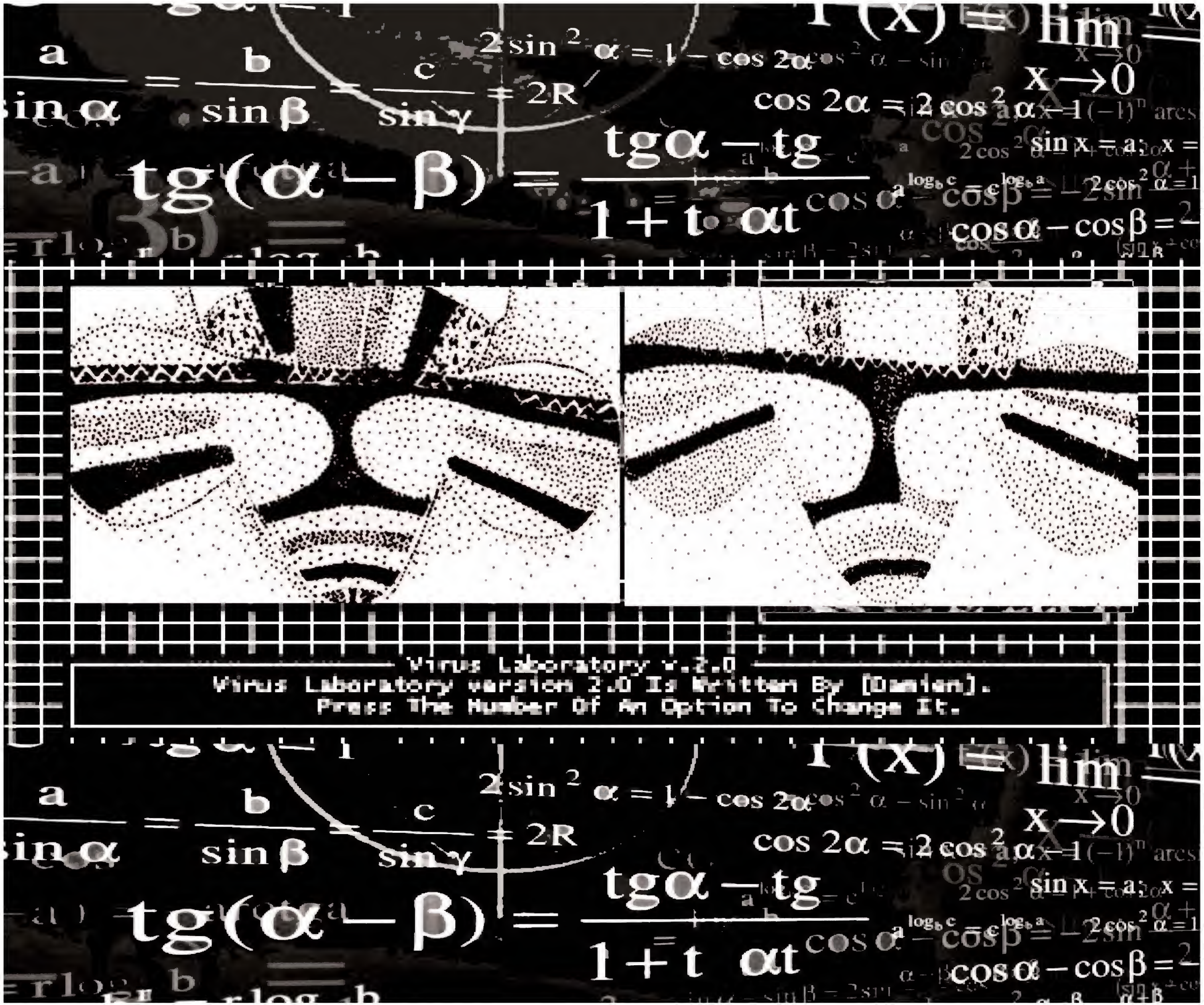




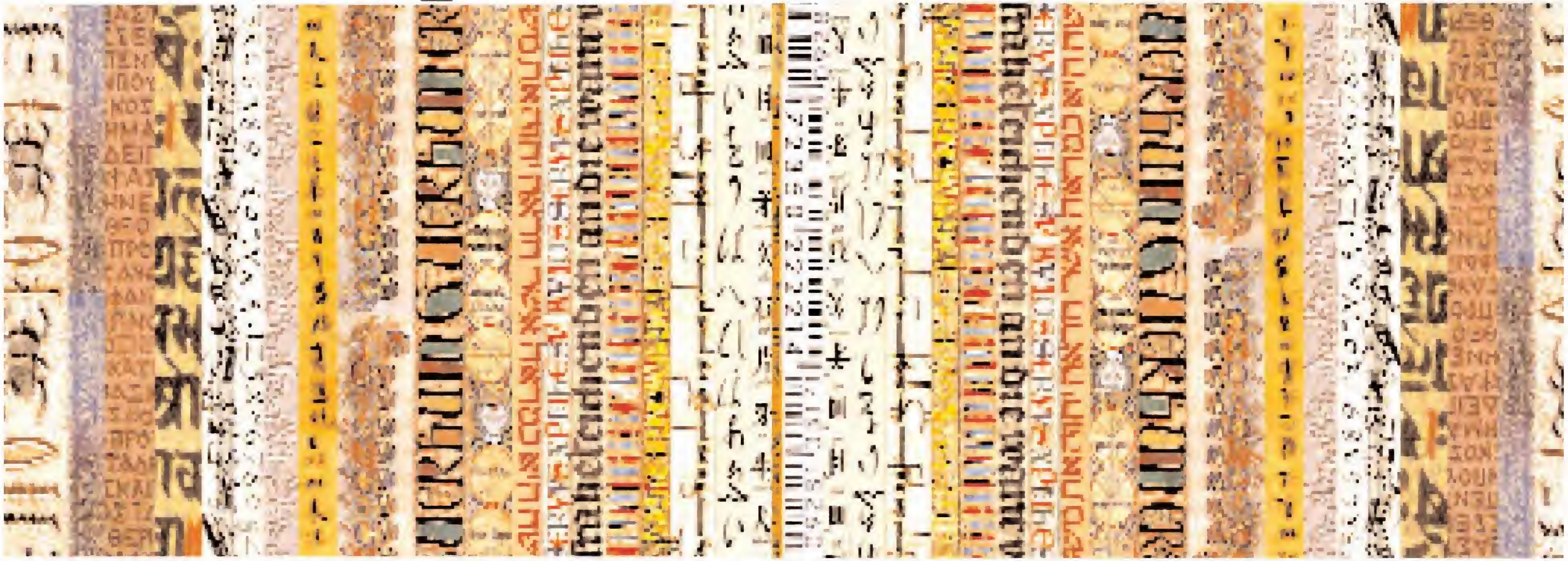

V=√(T/P)
a=V²/R
Y=x²-4X+5
π=3,14159265
a+CHfo



Saturne
Lead
Jupiter
Mars
Iron
Sol
Gould
Venus
Copper
Mercury
Luna
Silver
Aes
Aer
Alumen
Amalgama
Aqua
Aqua Fortis
BRA
KET
Mensis
Nota bene
NB
Nox
Oleum
Precipitare
Pulvis
Purificare
Putrificare
QE
Spiritus Vini
Sulphur
Sulphur Philosophorum
Tartar
Sal tartari


Virus Laboratory v.2.0
Virus Laboratory version 2.0 Is Written By [Damien].
Press The Number Of An Option To Change It.

f(q,p)mmmm99.[-i.W(f),-i.W(g)] := -i.W({f,g}).{f,g} q^2p^2 /6(Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2).[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -3/2).f(q,p).[-i.W(f),-i.W(g),,ni.W({f,g}).{f,g} q^2p^2 /6(Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2).[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -3/2).f(q,p).[-i.W(f),-i.W(g)] := -i.W({f,g}).{f,g} q^2p^2 /6(Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2).[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -3/2).f(q,p).[-i.W(f),-i.W(g)] := -i.W({f,g}).{f,g} q^2p^2 /6(Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2).[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -3/2).W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ8z8-9#566q^2p^2) = 9/6 (Q^2P^2 + QPQP +.[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -3/2).Or [Q^3, P^3]= 9 P^2Q^2 +18 i PQ -6 d 6iPQ -3/2).f(q,p).[-55t W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + 9UUYT +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -3/2).W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= Or [Q^3, P^3]= 9 P^2Q^2 +18 i PQ -6 d =(V+v) t = Vt +vt 1/299.792.458 3P^2Q^2 +6iPQ -3/2).3P^2Q^2 +6iPQ -3/2).3P^2Q^2 +6iPQ -3/2).q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -88iPQ -3/2).3P^2Q^2 +6iPQ -3/2).3P^2Q^2 +6iPQ -3/2).q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6.[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -3/2).Or



i.W(f),-i.W(g)] := -i.W({f,g}).{f,g} q^2p^2 /6(Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ +^{3}] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + RPQi.W({f,g}).{f,g} q^2p^2 /6(Q^2P^2 + QPQP + 458 P^2Q^2).[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -3/2).f(q,p).[-i.W(f),-i.W(g)] := -i.W({f,g}).{f,g} q^2p^2 /6(Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2).[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -3/2).f(q,p).[-i.W(f),-i.W(g)] := -i.W({f,g}).{f,g} q^2p^2 /6(Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2).[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -3/2).W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ8z8-9#566PQPQ + P^2Q^2).[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q 6ttr38zz9000f(q,p).[-i.W(f),-i.W(g)] := -i.W({f,g}).{f,g} q^2p^2 /6(Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2).[W(q^3),W(p^3] et UTT66+ QP^2Q + PQ^2P + PQPQ + P^2Q^2).[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQx^3,p^3}=3q^2.3p^2-0.QP = PQ +-i.W({f,g}).{f,g} q^2p^2 /6(Q^2P^2 + Or [Q^3, P^3]= 9 P^2Q^2 +18 i PQ -6 d =(V+v) t = Vt +vt 1/299.792.458 3P^2Q^2 +6iPQ -3/2).3P^2Q^2 +6iPQ -3/2).3P^2Q^2 +6iPQ -3/2).q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -88 PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2)= 3 (3P^2Q^2 +6iPQ -3/2).3P^2Q^2 +6iPQ -3/2).f(q,p).[-i.W(f),-i.W(g)] := -i.W({f,g}).{f,g} q^2p^2 /6(Q^2P^2 + QPQP + QP^2Q + PQ^2P + PQPQ + P^2Q^2).[W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 + QPQP + QP^2Q0005577890 +6iPQ -3/2).Or [Q^3, P^3]= 9 P^2Q^2 +18 i PQ -6 d =(V+v) t = Vt +vt 1/299.792.458 [W(q^3),W(p^3] et {x^3,p^3}=3q^2.3p^2-0.QP = PQ +i :9 W(q^2p^2) = 9/6 (Q^2P^2 +f(q,p).[-i.W(f),-i.W(g)] := -i.W({f,g}).{f,g}


$\hbar^2 \frac{\partial^2\Psi(\vec{r},t)}{\partial t^2} = -\hbar^2 c^2 \Delta \Psi(\vec{r},t) + m^2 c^4 \Psi(\vec{r},t)$
$R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R - \Lambda g_{\mu\nu} = \frac{8\pi G}{c^4} T_{\mu\nu}$
$\Delta A \cdot \Delta B \geq \frac{1}{2} \left| \left\langle [\hat{A}, \hat{B}] \right\rangle_\gamma \right|$

$p + n - D + \gamma$ (γ : pl

$D + n - {}^3H + \gamma$

$D + p - {}^3He + \gamma$

$D + D - {}^3H + p$

$D + D - {}^3He + n$

$D + D - {}^4He + \gamma$

${}^3H + p - {}^4He + \gamma$

${}^3He + n - {}^3H + p$

${}^3He + n - {}^4He + \gamma$

${}^3H + D - {}^4He + n$

${}^3He + D - {}^4He + p$

${}^3He + {}^3He - {}^4He + 2p$

${}^4He + D - {}^6Li + \gamma$

${}^4He + {}^3H - {}^7Li + \gamma$

${}^4He + {}^3He - {}^7Be + \gamma$

${}^6Li + n - {}^7Li + \gamma$

${}^6Li + p - {}^7Be + \gamma$

${}^7Li + p - {}^4He + \gamma$

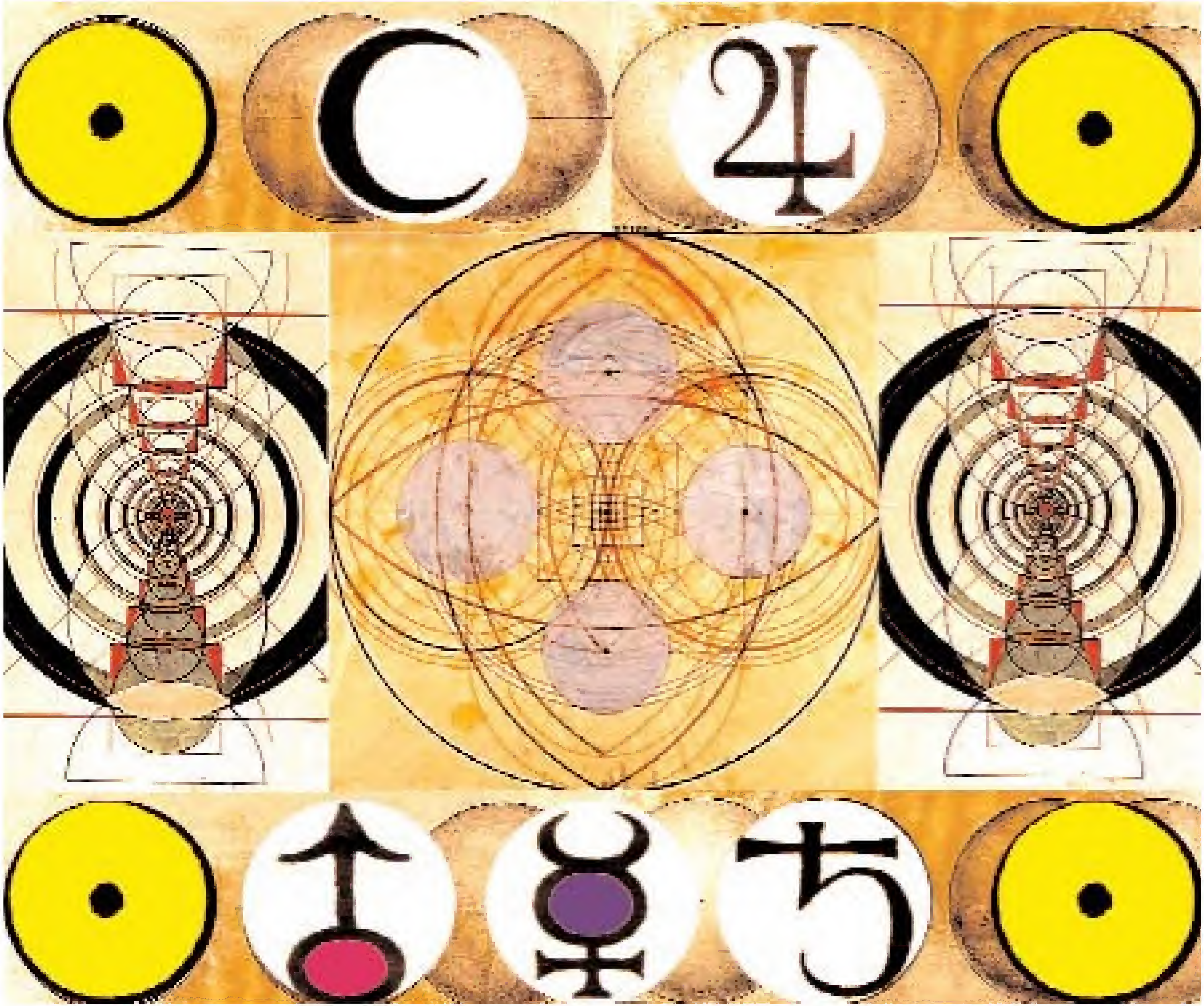
${}^7Be + n - {}^7Li + p$

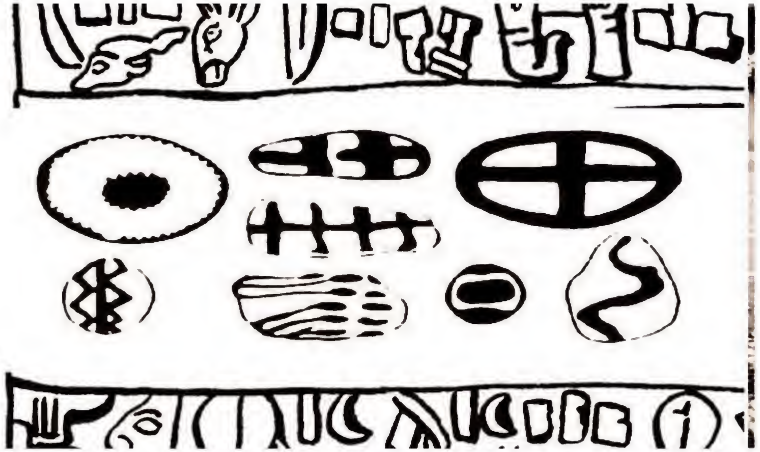
${}^7Be + e^- - {}^7Li + \gamma$

$$n + \nu_e \leftrightarrow p + e^-$$
$$n + e^+ \leftrightarrow p + \nu_e$$
$$n \leftrightarrow p + e^- + \overline{\nu_e}$$

$$\frac{n_p}{n_n} = e^{-\frac{E_p - E_n}{kT}} = e^{-\frac{\Delta mc^2}{kT}}$$

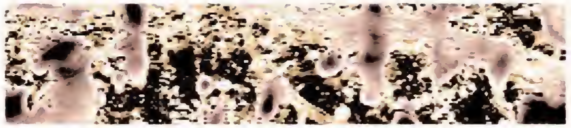

WAVE
AXIS
DYNAMIC





$$\lambda_{max} = \frac{hc}{4,965 \cdot kT} = \frac{2,898 \cdot 10^{-3}}{T}$$

$$\Delta\varphi = \varphi_{exp} - \varphi_{RG} = \Delta\varphi_{Newton} - \varphi_{Einstein} \simeq 0.08 \pm 0.45$$



$$\lambda = \frac{h}{p}$$

$$\vec{F}_{12} = -G\frac{m_1 m_2}{d^2}\vec{u}_{12}$$

$$H = \sum_k a_k^\dagger a_k$$

$$\varphi_{Einstein} = \frac{6\pi G M_S}{c^2 a (1-e^2)} \quad \frac{24\pi^3 a^2}{T^2 c^2 (1-e^2)}$$

$$R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R - \Lambda g_{\mu\nu} = \frac{8\pi G}{c^4}$$

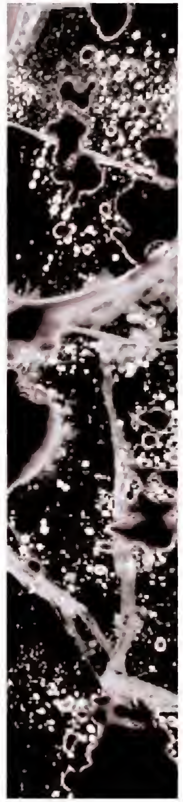
g(0)=a ; g(n+1)=f(g(n))y=g(x) ? ? l [â(l,0)=a ? ? i < x â(l, i+1)=f(â(l, i)) ? y = â(l, x)]

g(0)=a ; g(n+1)=f(g(n))y=g(x) ? ? l [â(l,0)=a ? ? i < x â(l, i+1)=f(â(l,

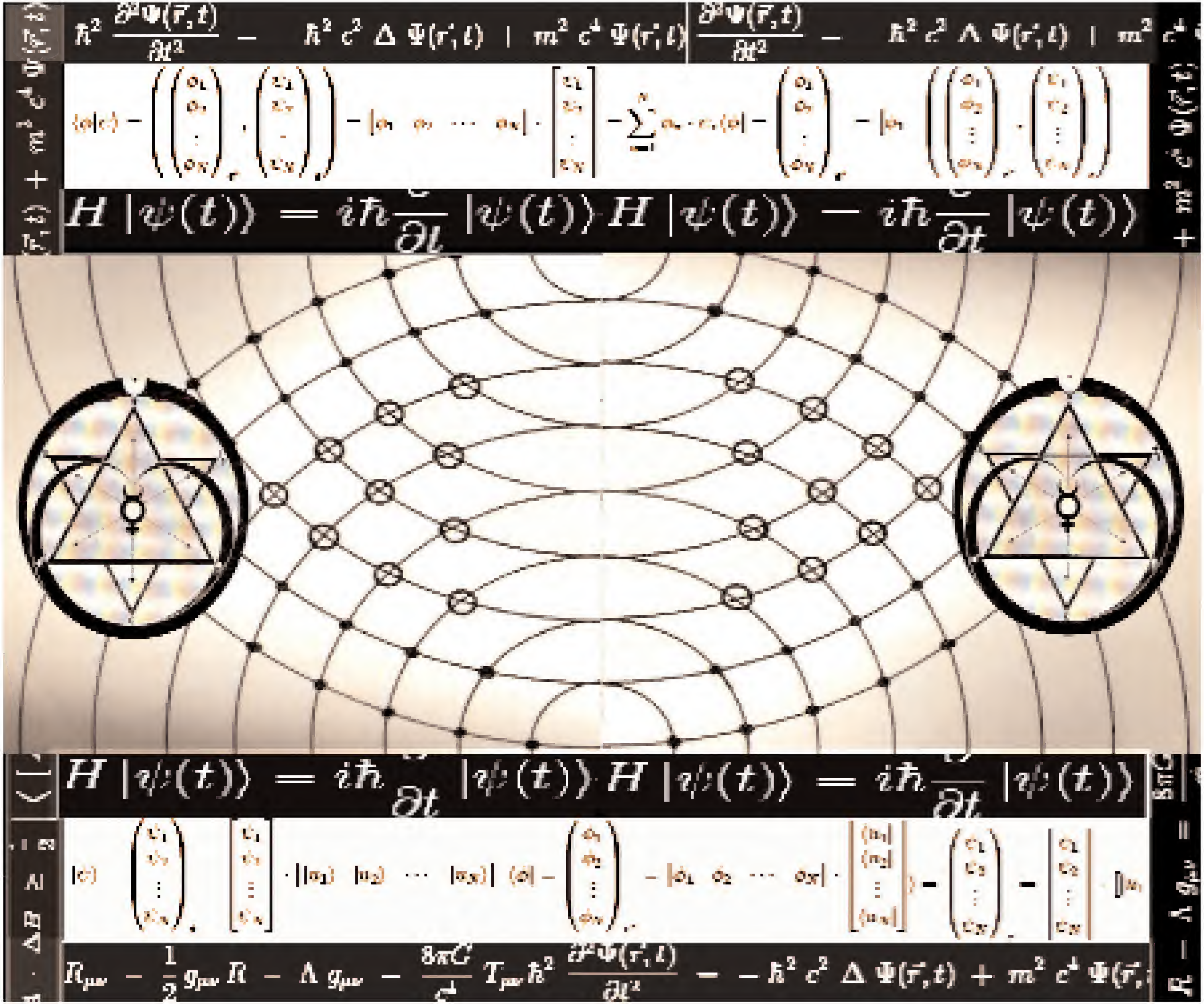
g(0)=a ; g(n+1)=f(g(n))y=g(x) ? ? l [â(l,0)=a ? ? i < x â(l, i+1)=f(â(l, i)) ? y = â(l, x)]

?x A ? ?x B ? ?x (A ? B) ; ?x ?y A(x, y) ?N ?z ?x?z ?y?z A(x, y) ; ?x A

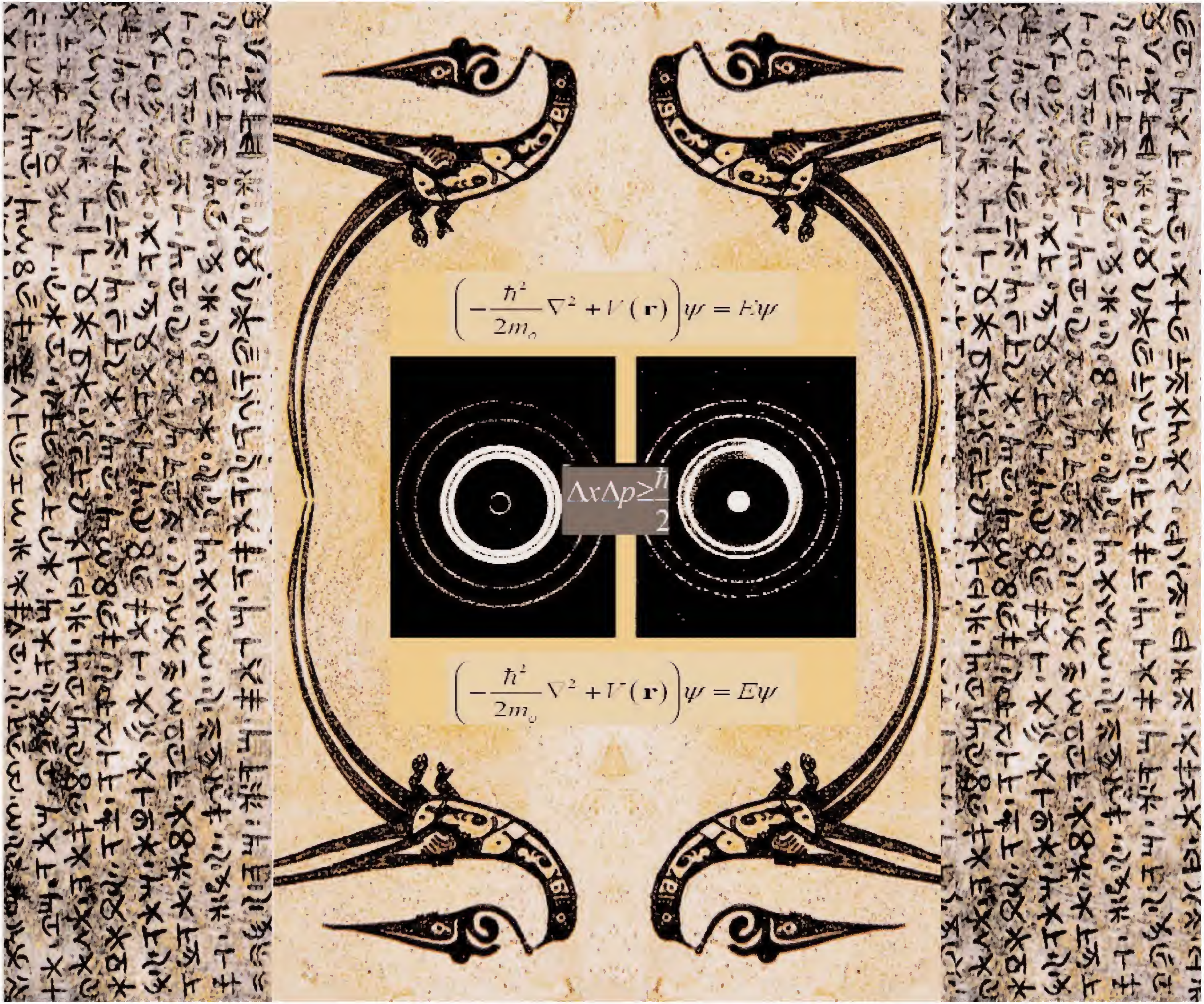
? ?y B ? ?x ?y (A ? B) ; ?x?z ?y A(x, y) ?N? u ?x?z ?y?u A(x, y).

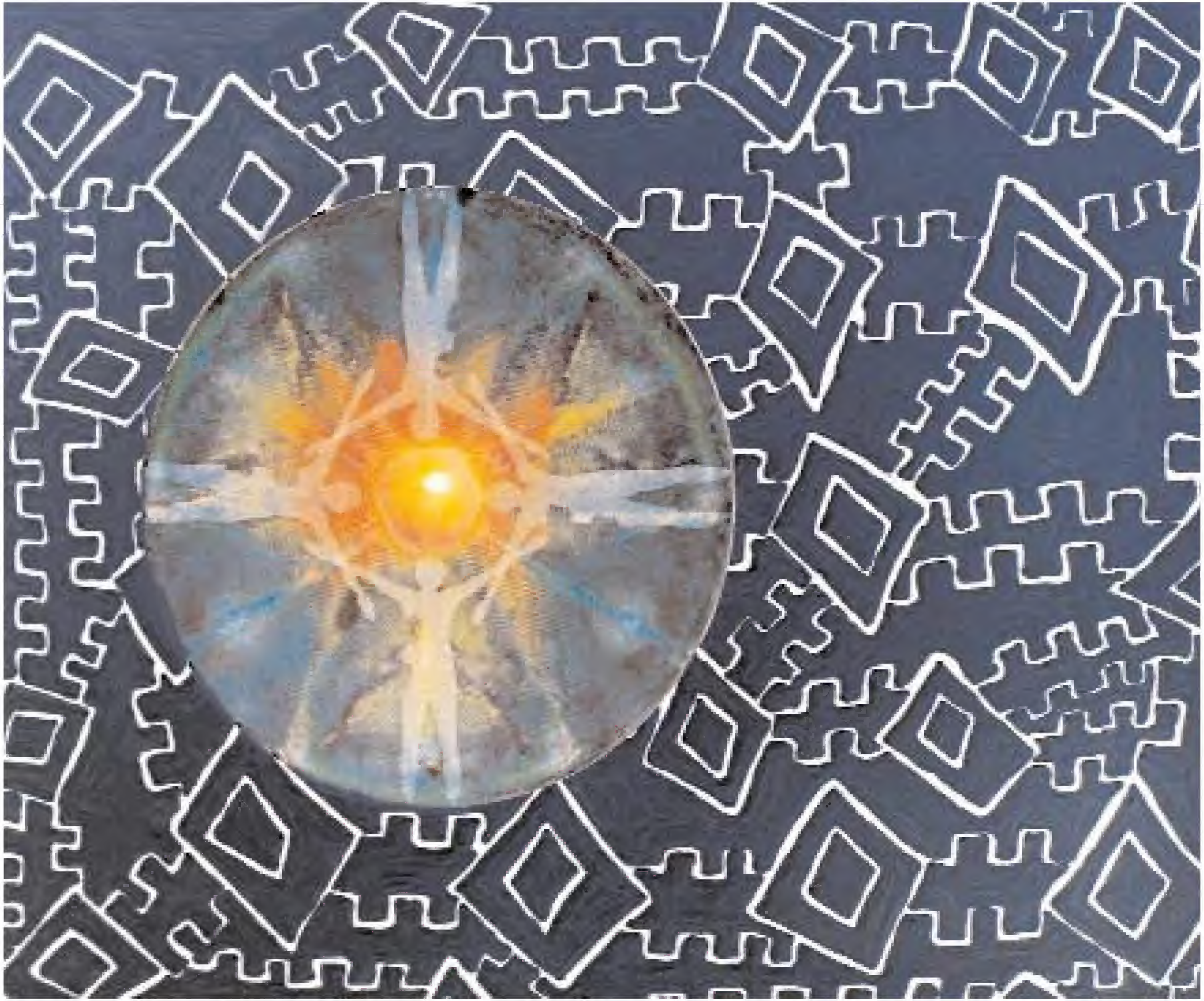


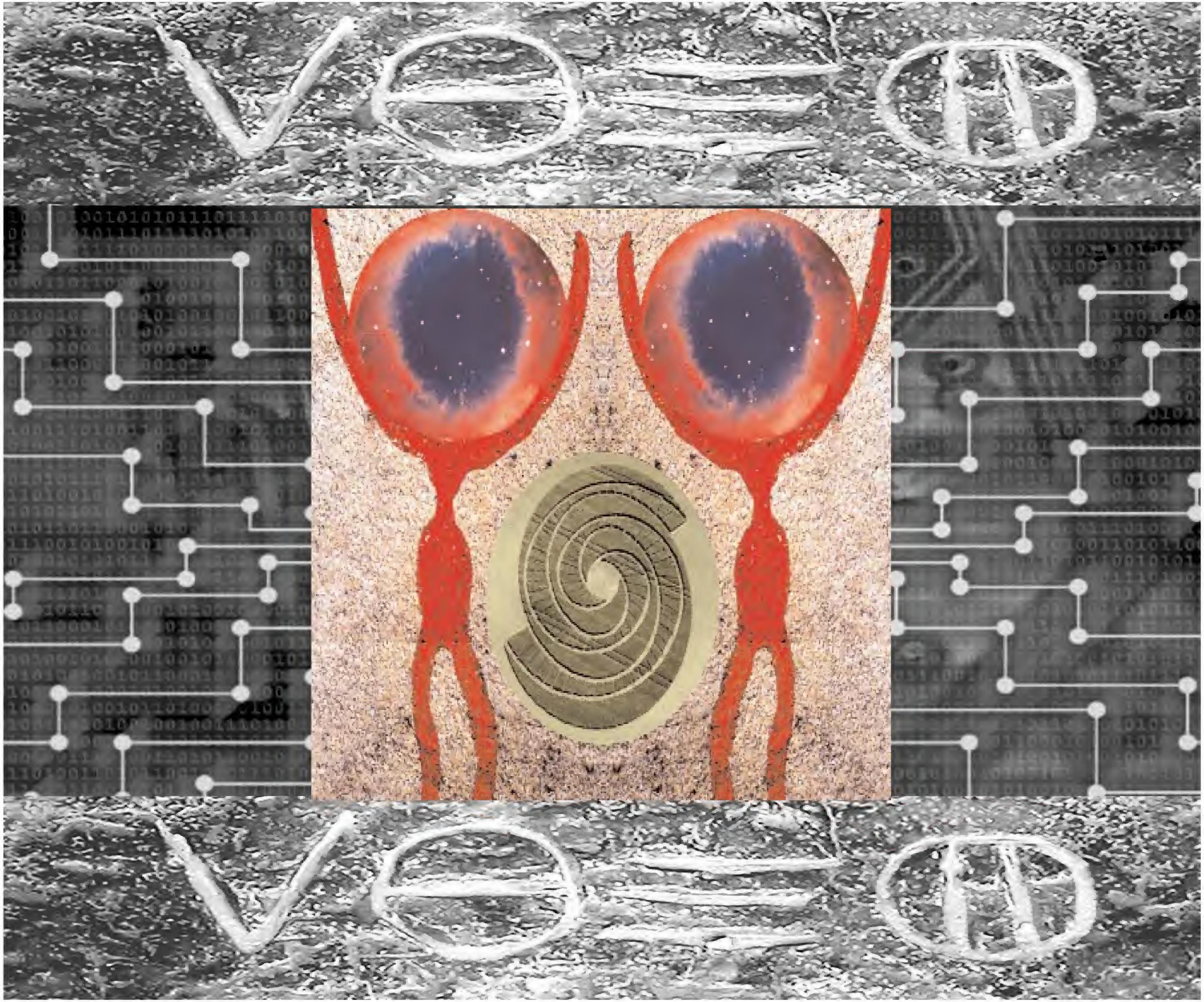
$$\Phi = \sigma T^4$$

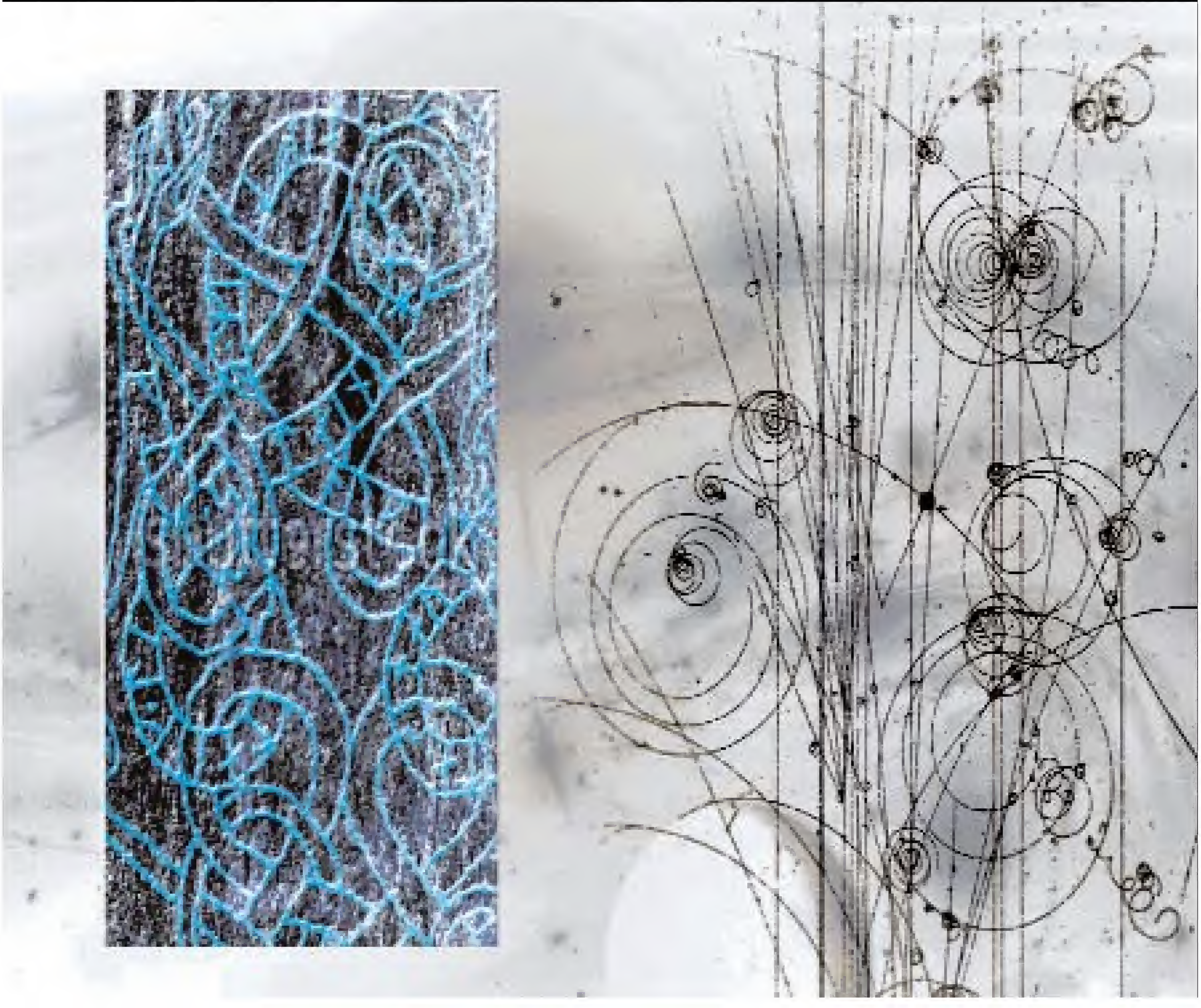


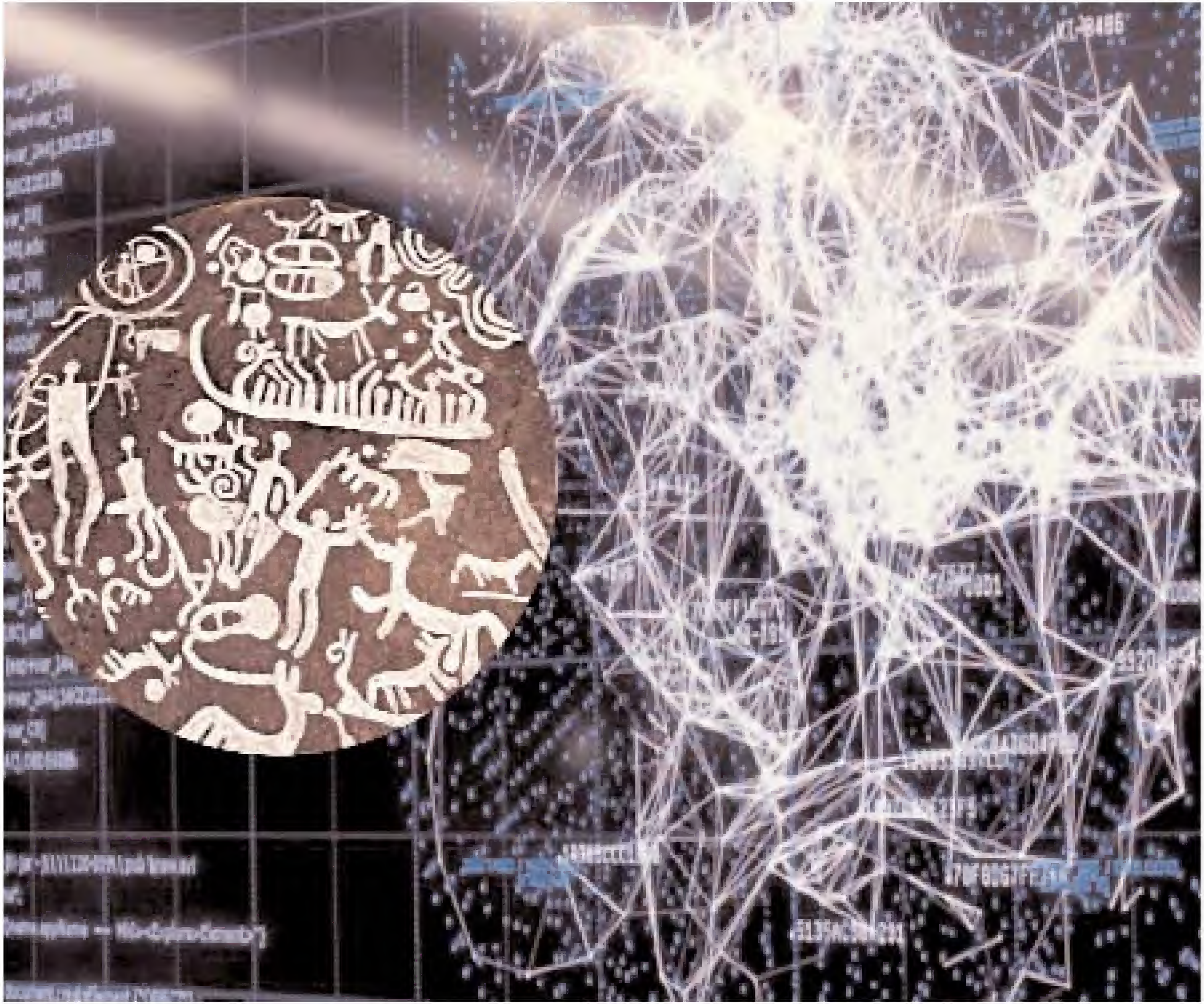
$H\,|\psi(t)\rangle = i\hbar\frac{\partial}{\partial t}\,|\psi(t)\rangle$
$R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R - \Lambda g_{\mu\nu} = \frac{8\pi G}{c^4} T_{\mu\nu}$

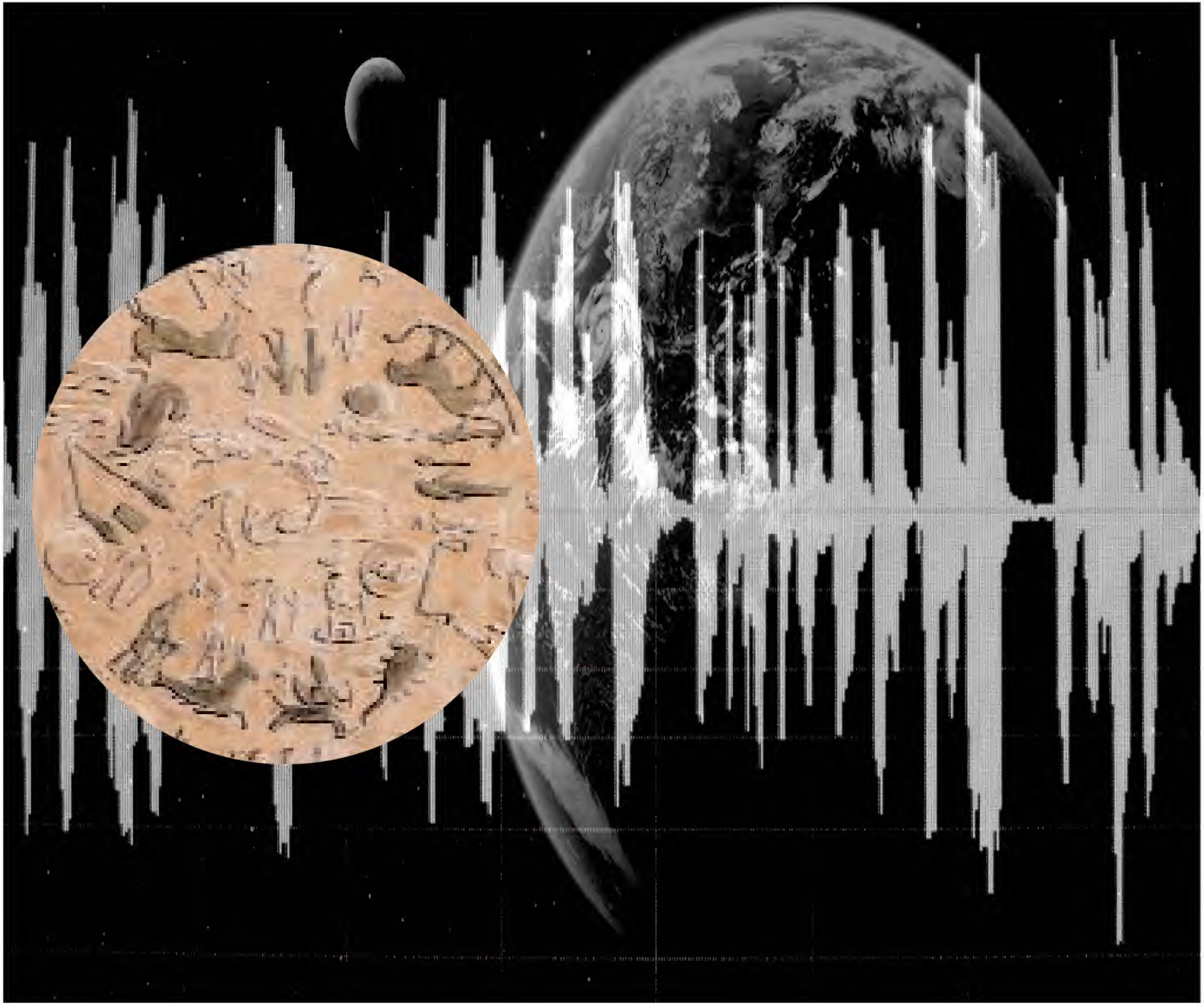

$\left(-\frac{\hbar^2}{2m_o}\nabla^2 + V(\mathbf{r})\right)\psi = E\psi$
$\Delta x \Delta p \geq \frac{\hbar}{2}$
$\left(-\frac{\hbar^2}{2m_o}\nabla^2 + V(\mathbf{r})\right)\psi = E\psi$

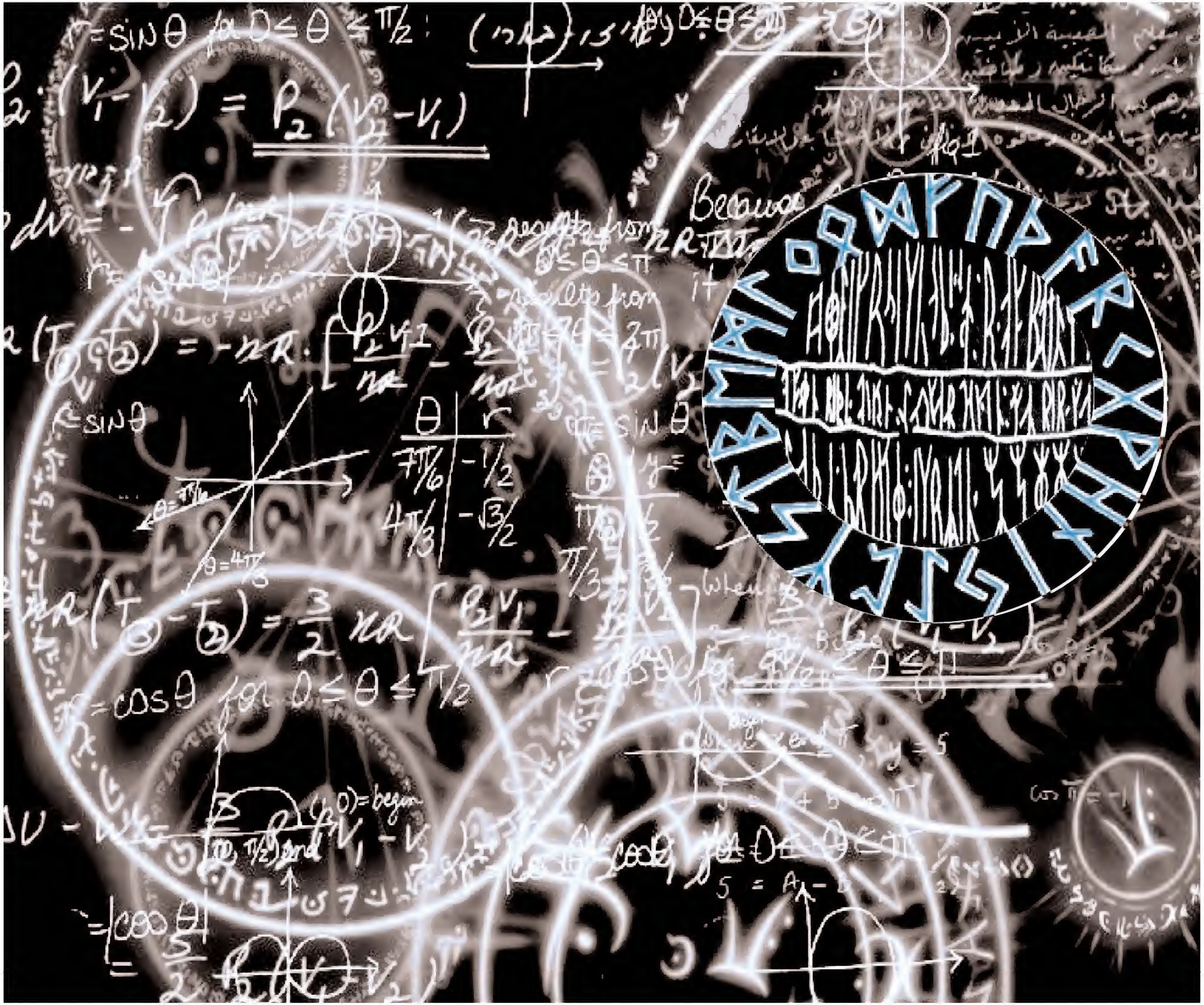




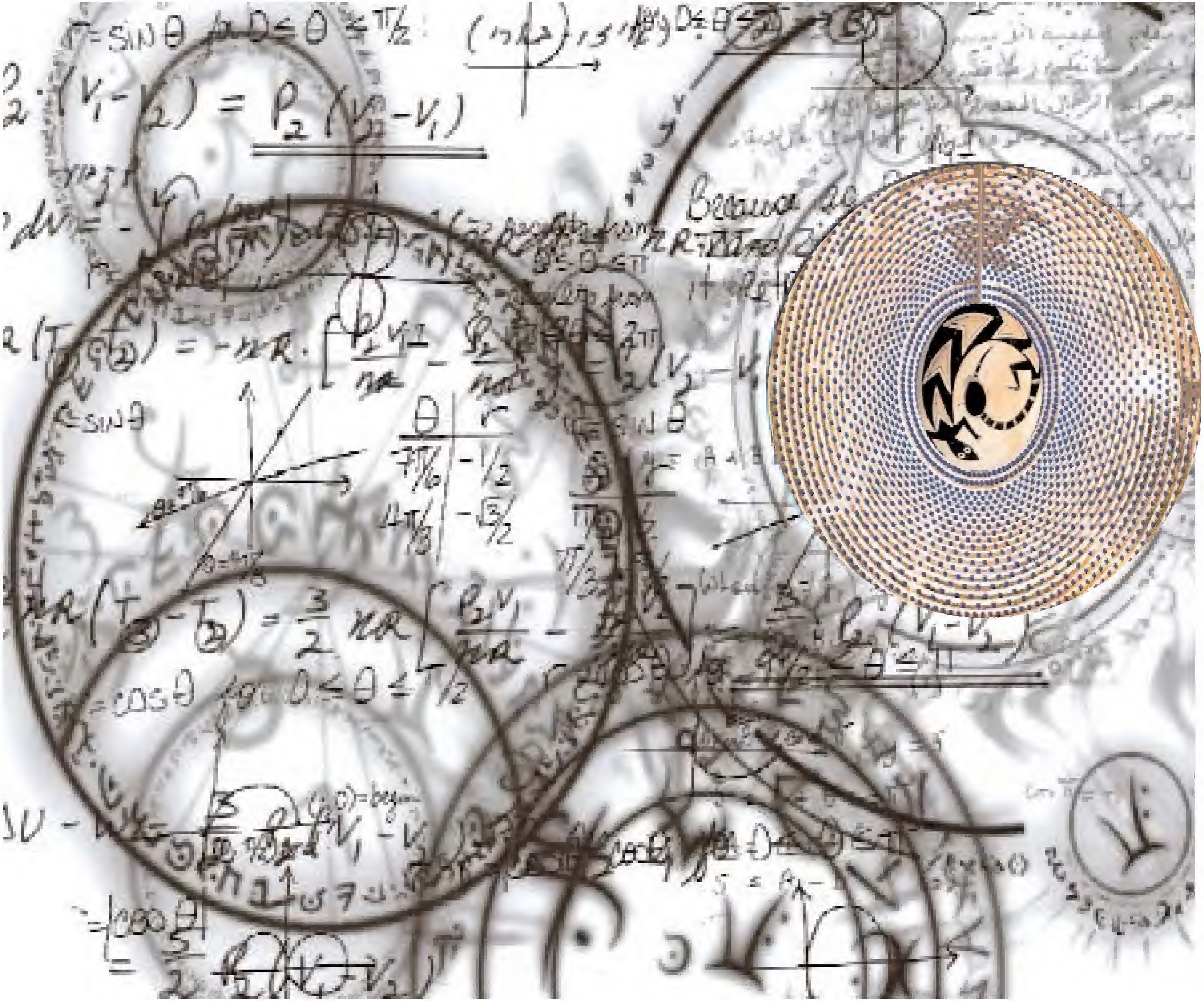




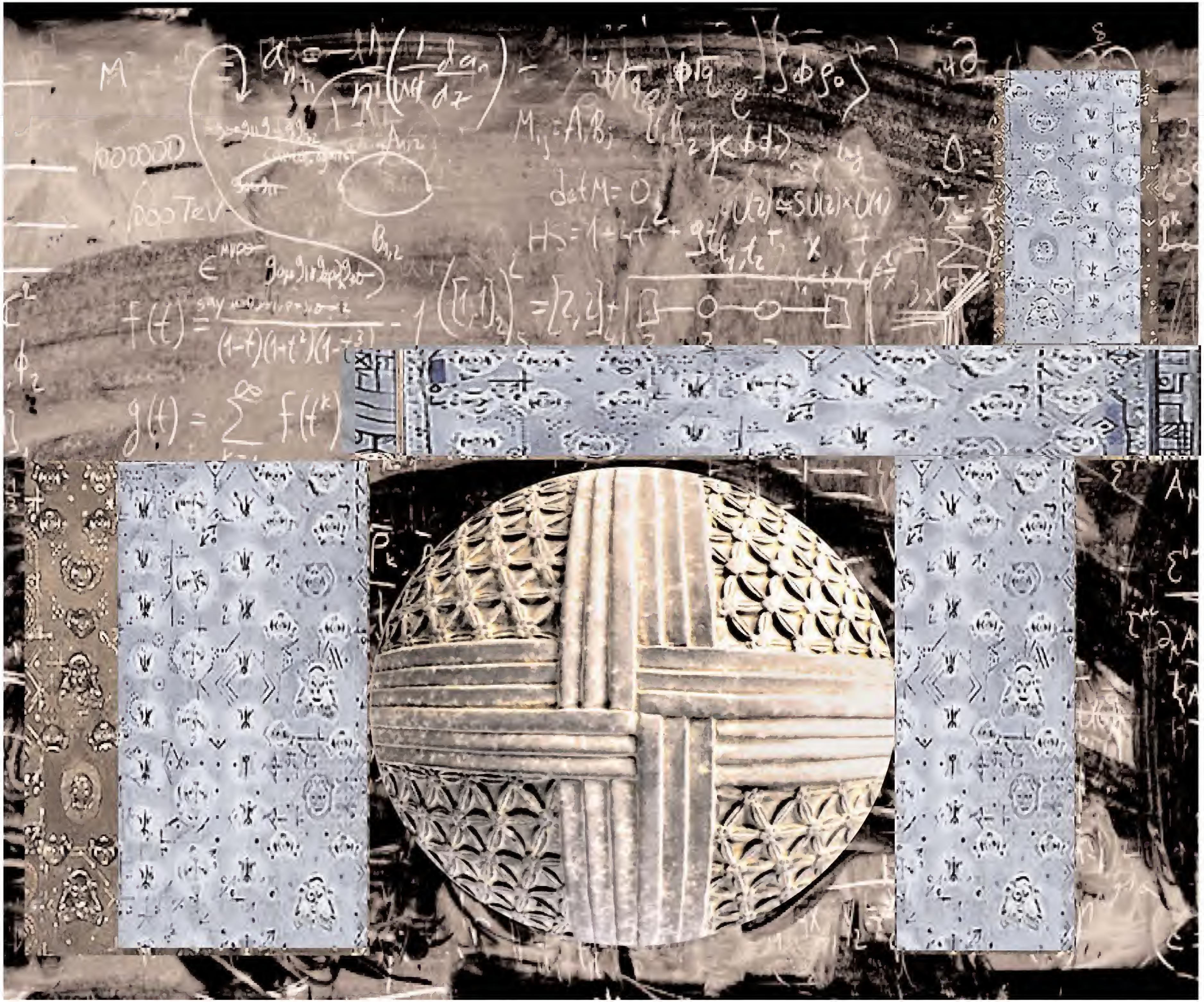


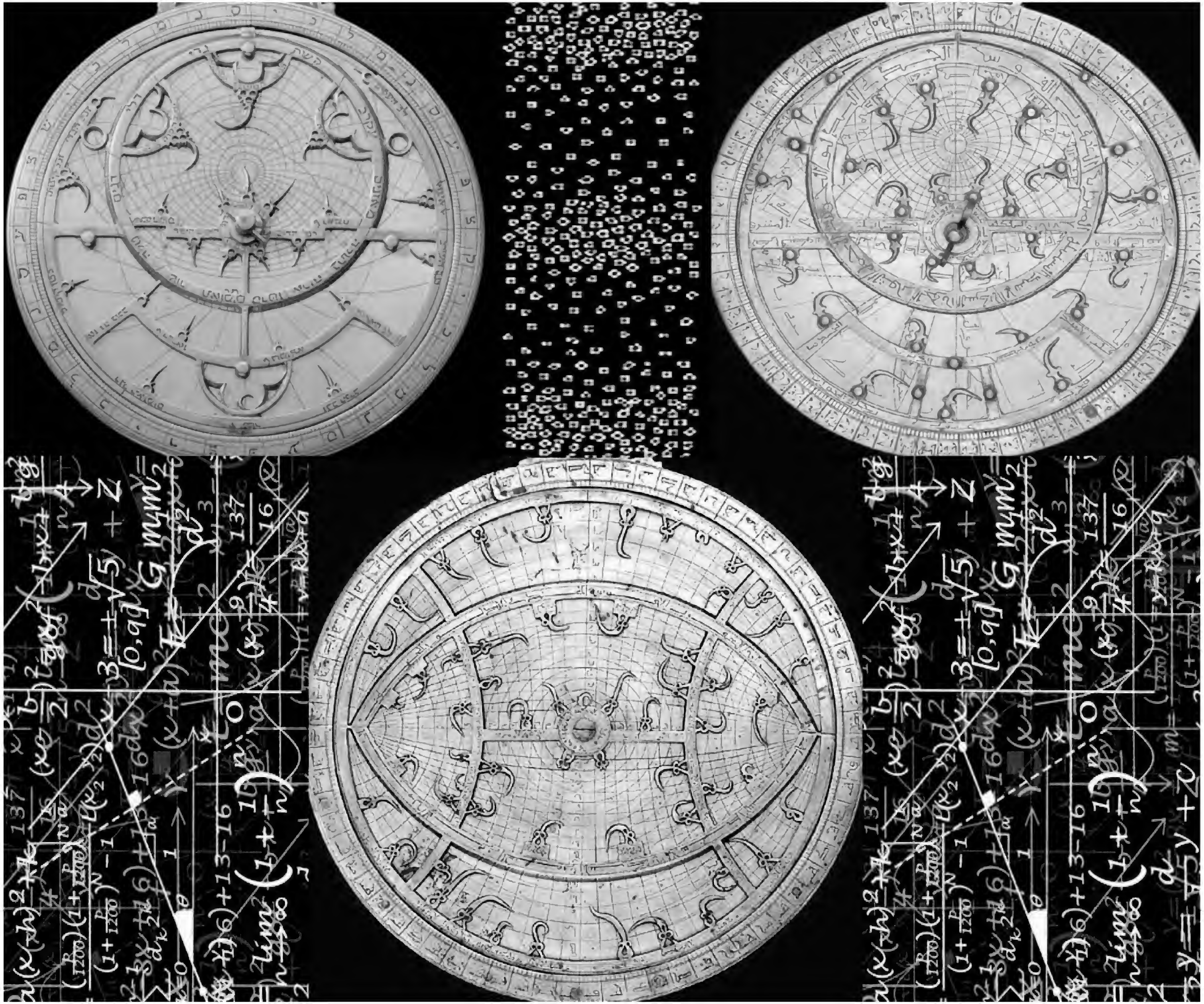


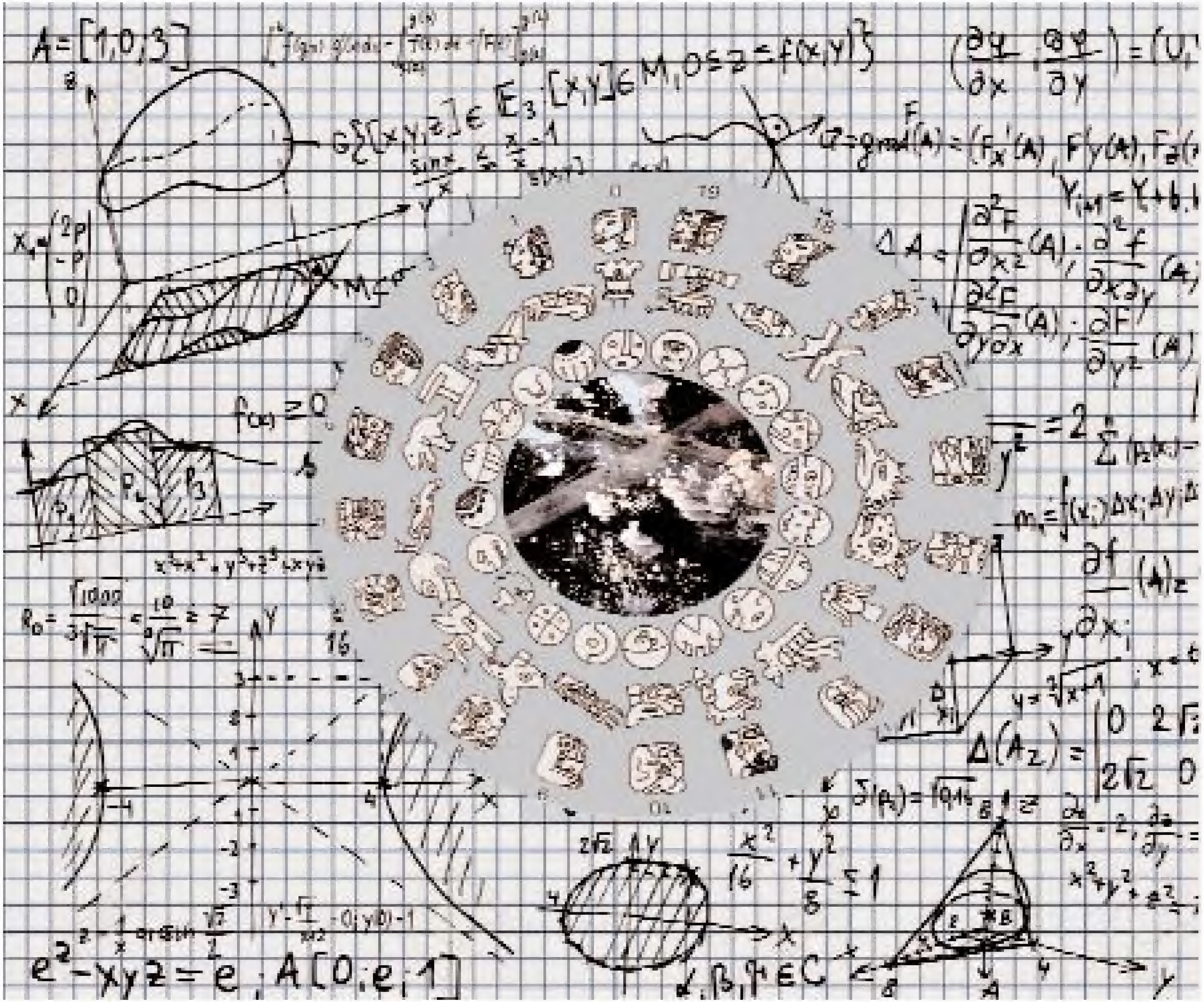
r = sin θ for 0 ≤ θ ≤ π/2
Because
r = cos θ for 0 ≤ θ ≤ π/2

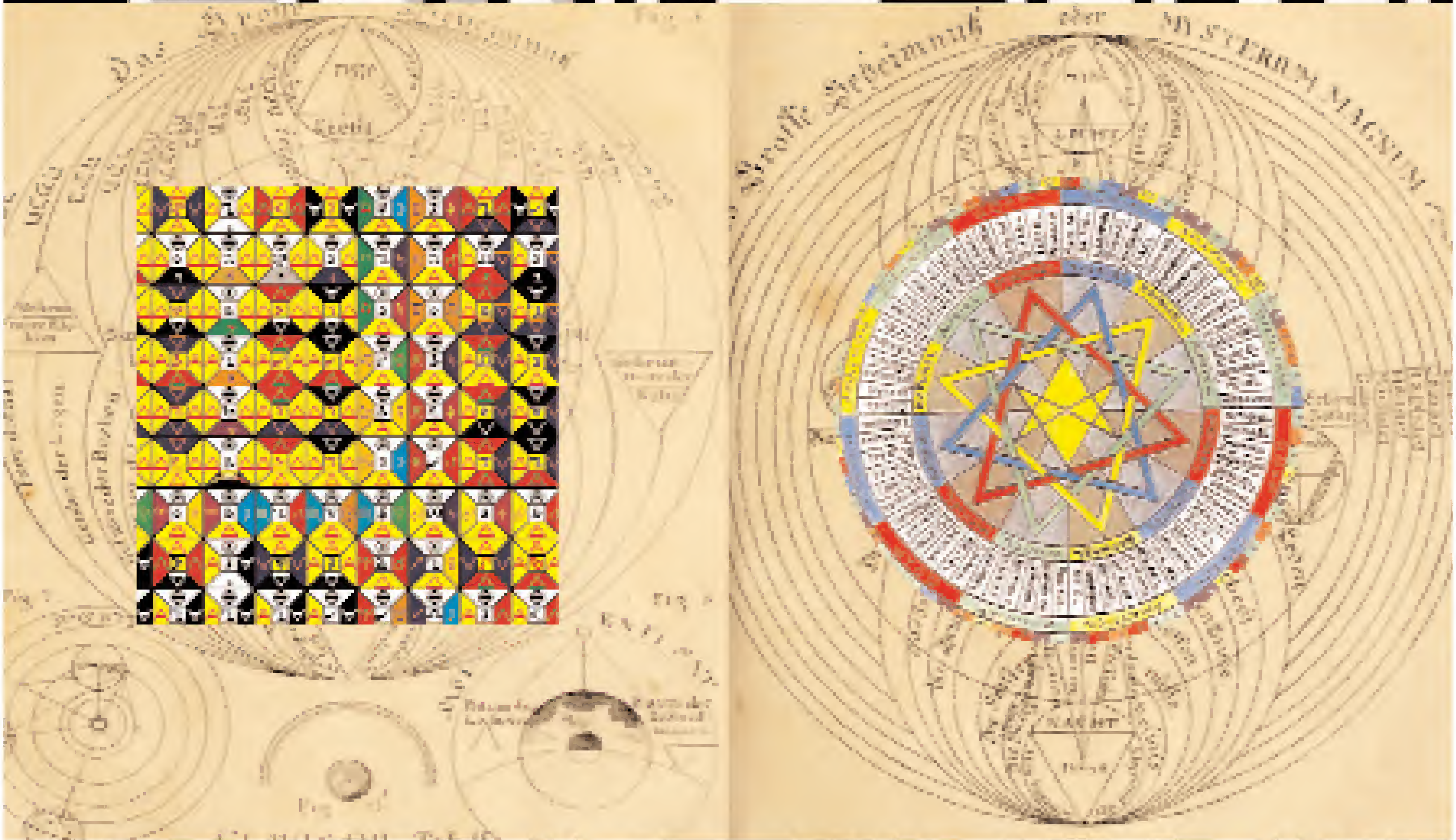


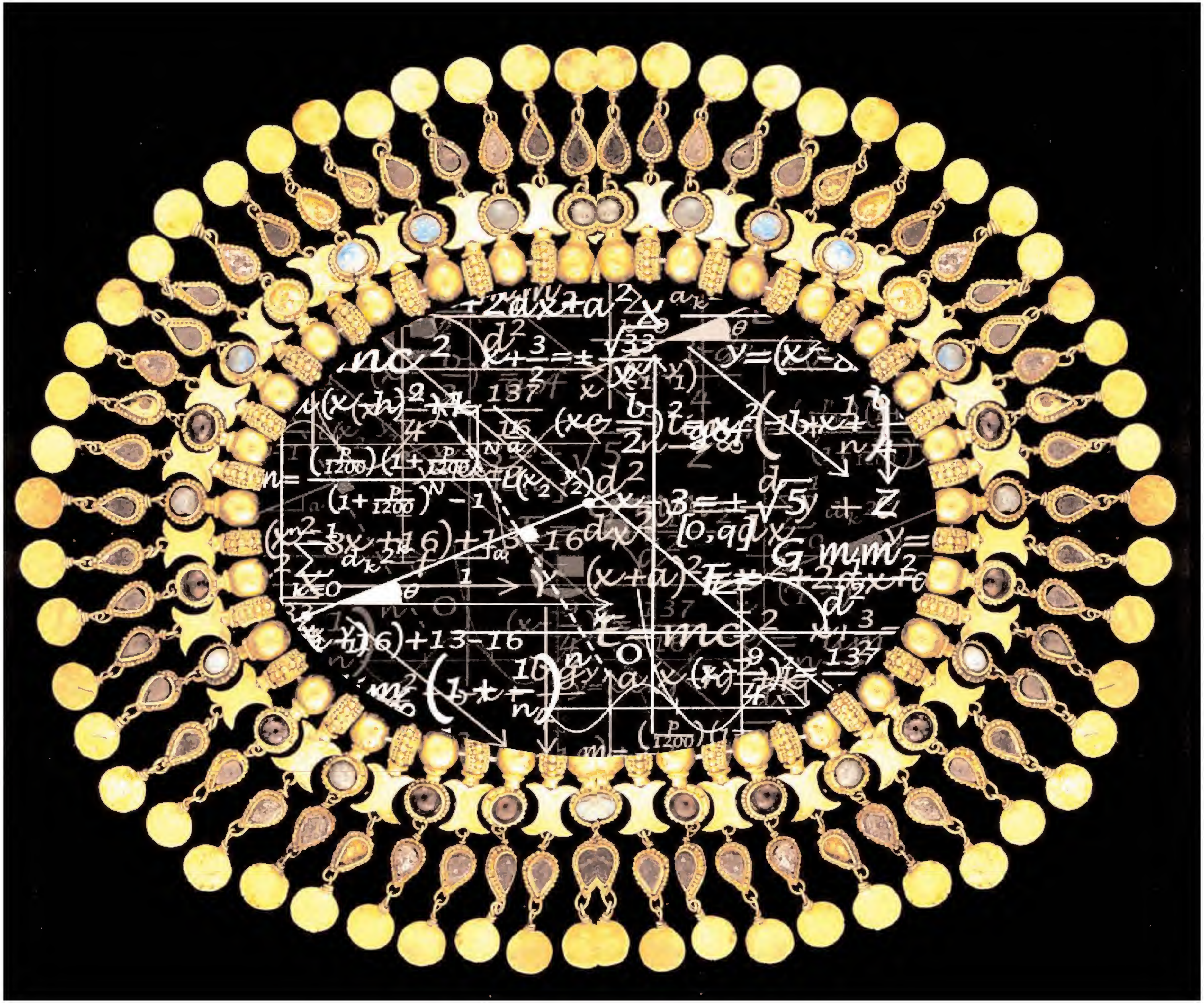
= SIN θ for 0 ≤ θ ≤ π/2
= COS θ for 0 ≤ θ ≤ π/2
Because

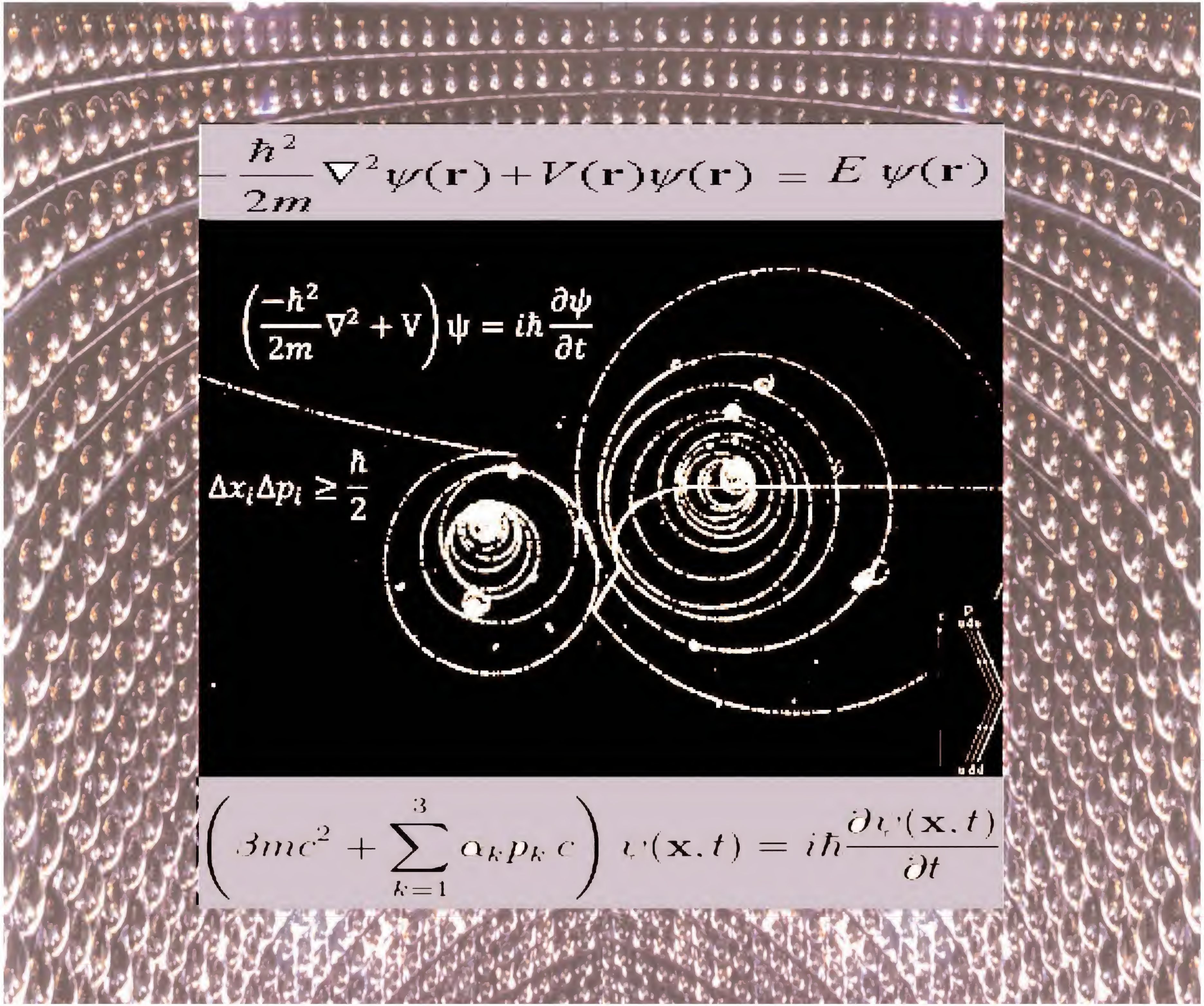


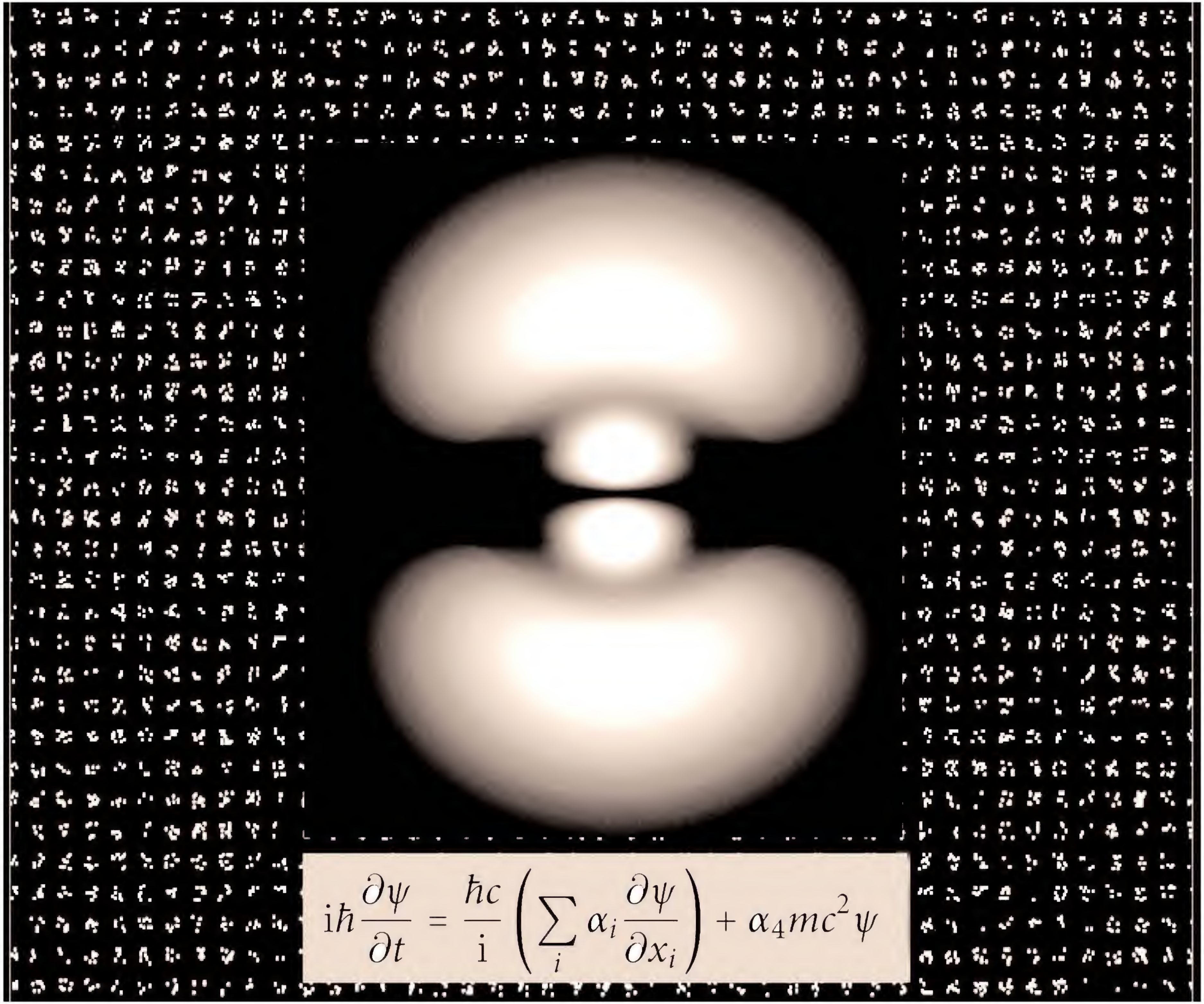




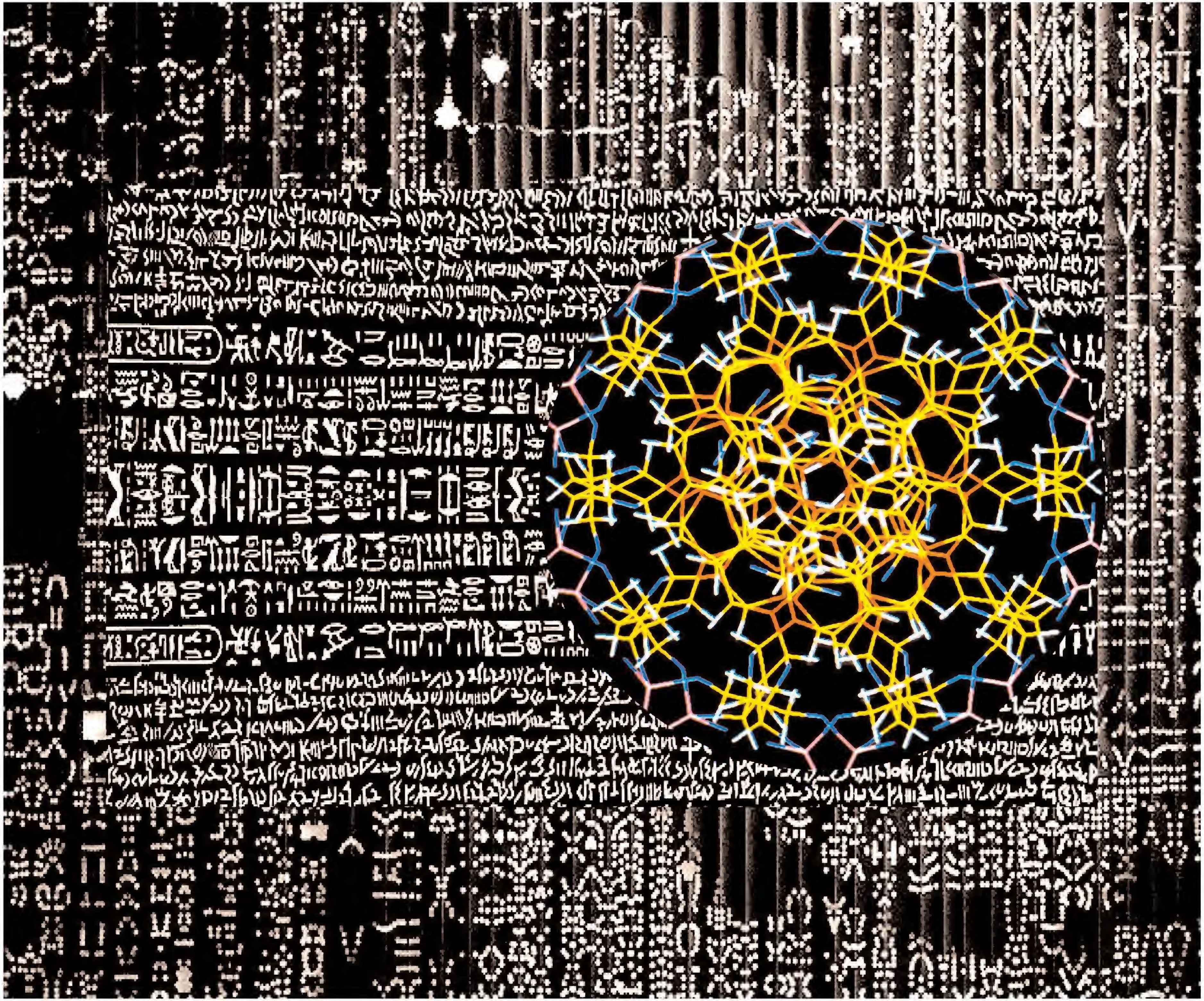


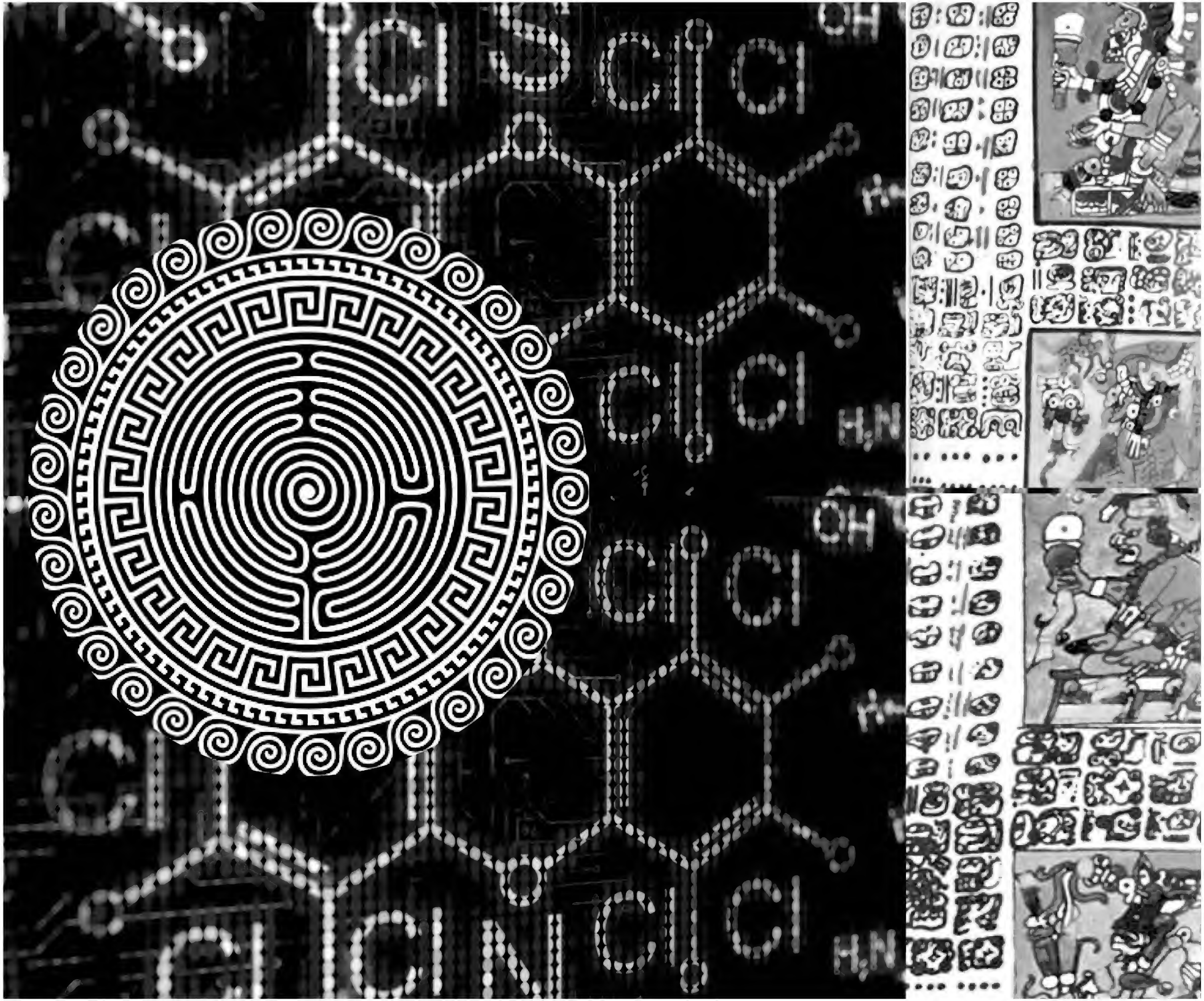



$-\frac{\hbar^2}{2m}\nabla^2\psi(\mathbf{r}) + V(\mathbf{r})\psi(\mathbf{r}) = E\,\psi(\mathbf{r})$
$\left(\frac{-\hbar^2}{2m}\nabla^2 + V\right)\psi = i\hbar\frac{\partial\psi}{\partial t}$
$\Delta x_i \Delta p_i \geq \frac{\hbar}{2}$
$\left(\beta mc^2 + \sum_{k=1}^{3} \alpha_k p_k c\right)\psi(\mathbf{x},t) = i\hbar\frac{\partial\psi(\mathbf{x},t)}{\partial t}$



$$i\hbar \frac{\partial \psi}{\partial t} = \frac{\hbar c}{i}\left(\sum_i \alpha_i \frac{\partial \psi}{\partial x_i}\right) + \alpha_4 mc^2 \psi$$



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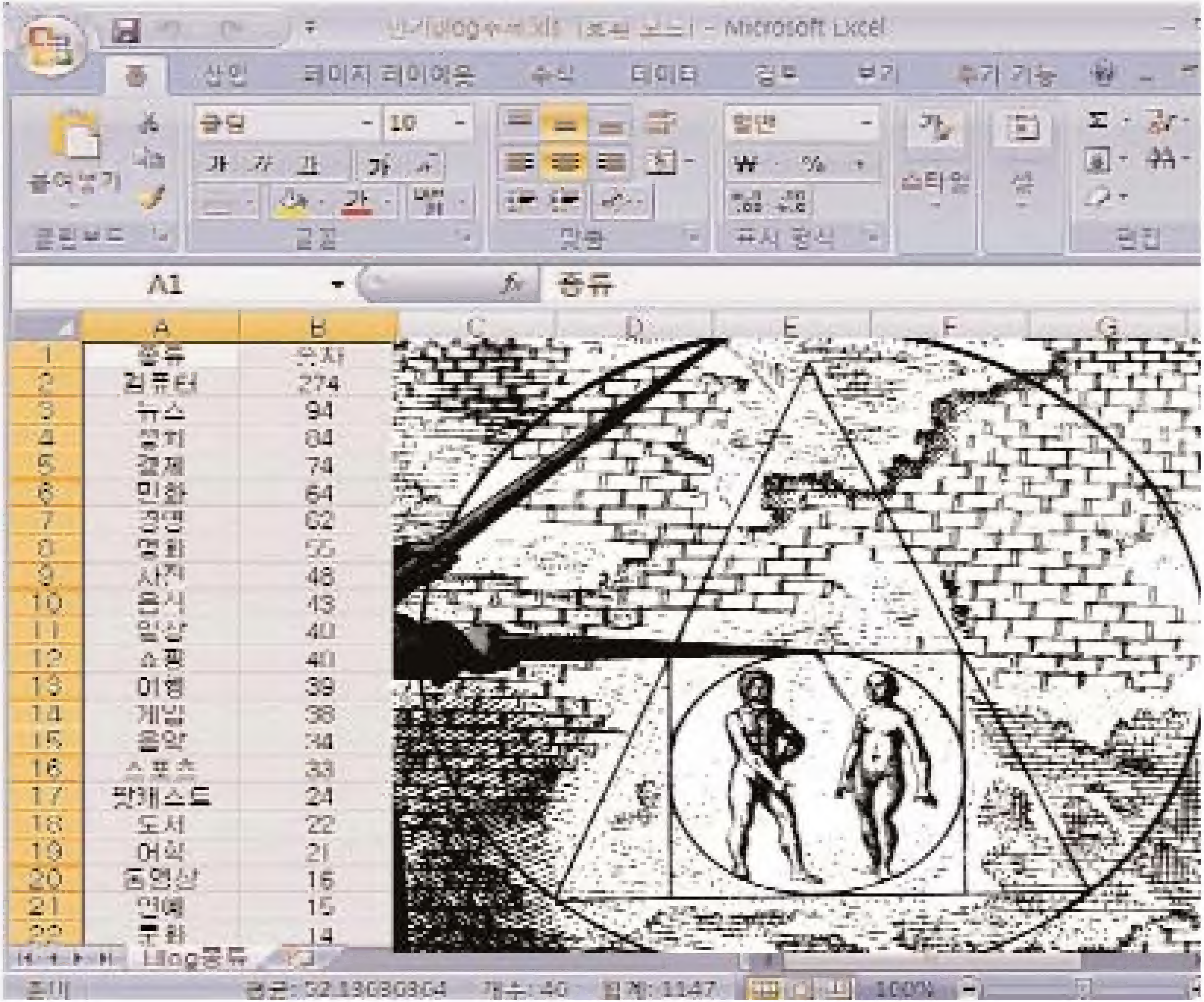
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음식 43
일상 40
쇼핑 40
여행 39
게임 38
음악 34
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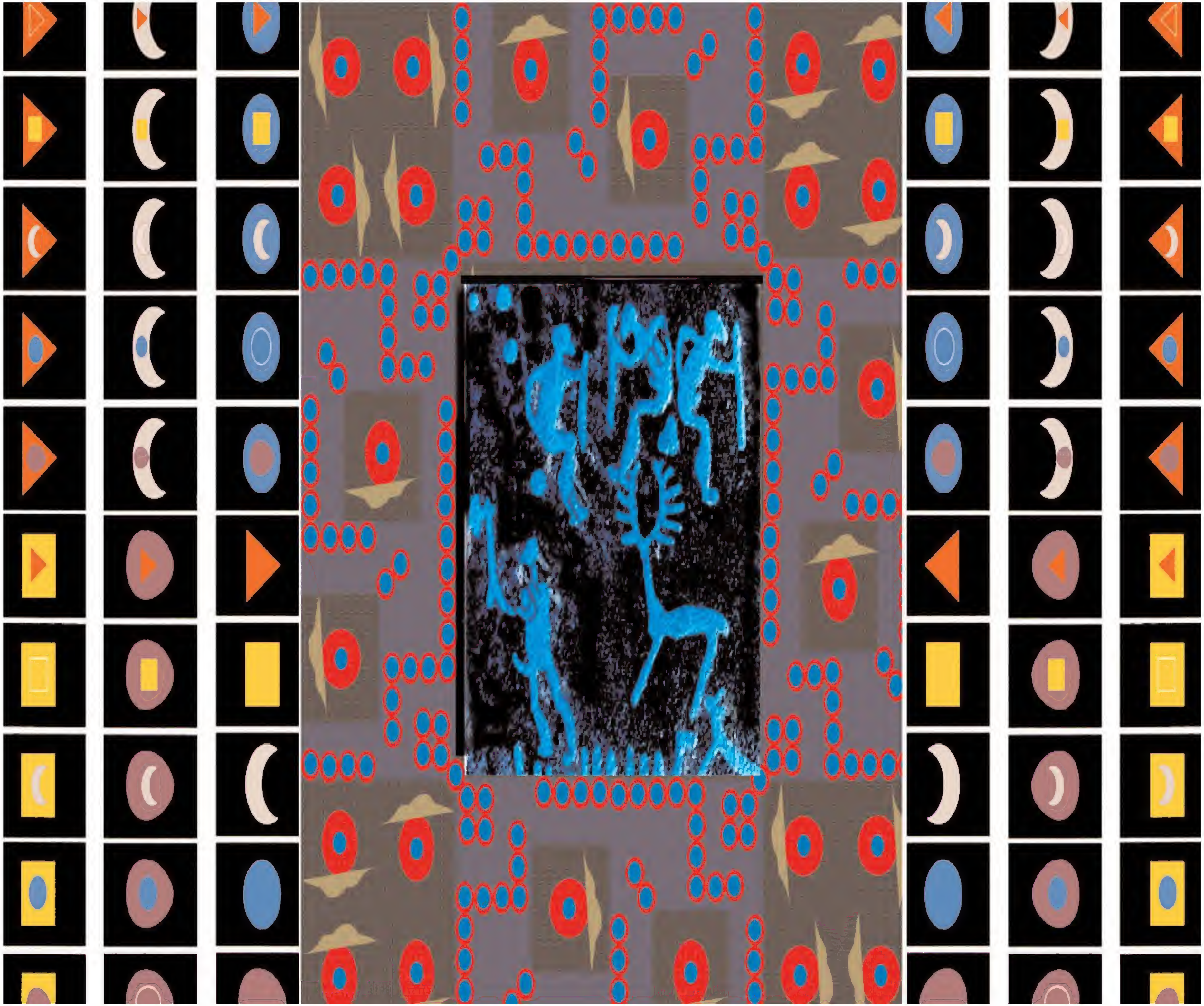
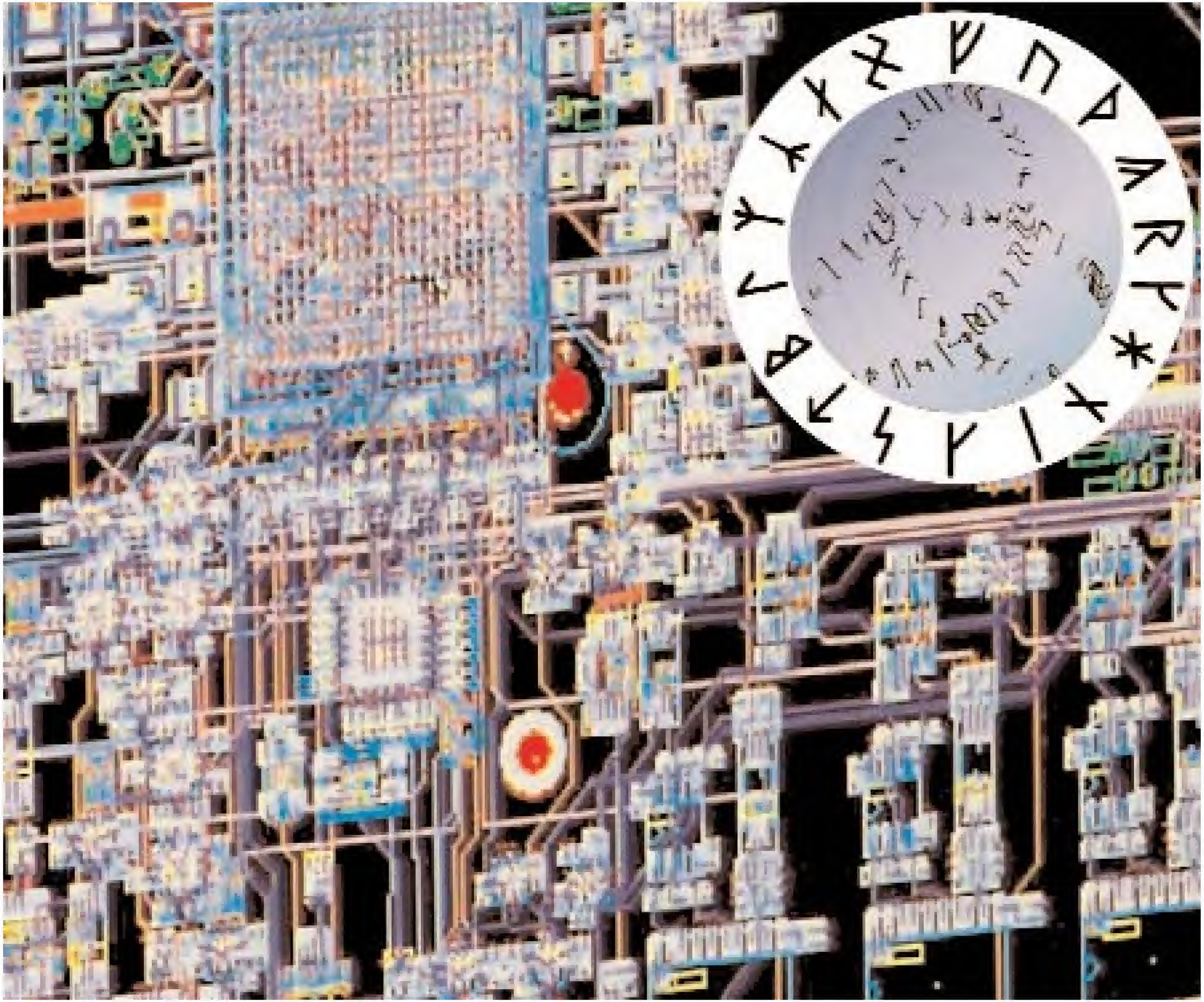
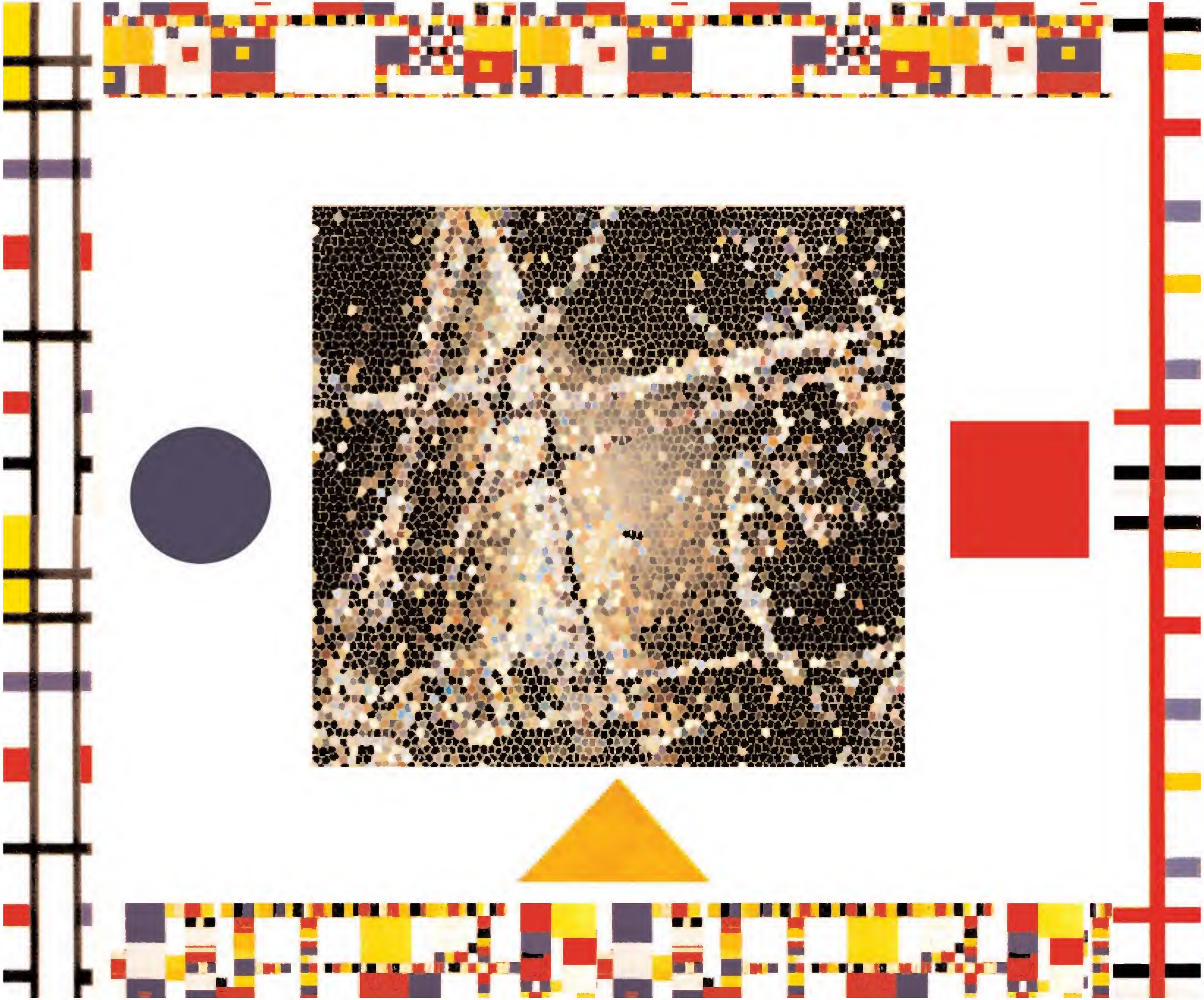
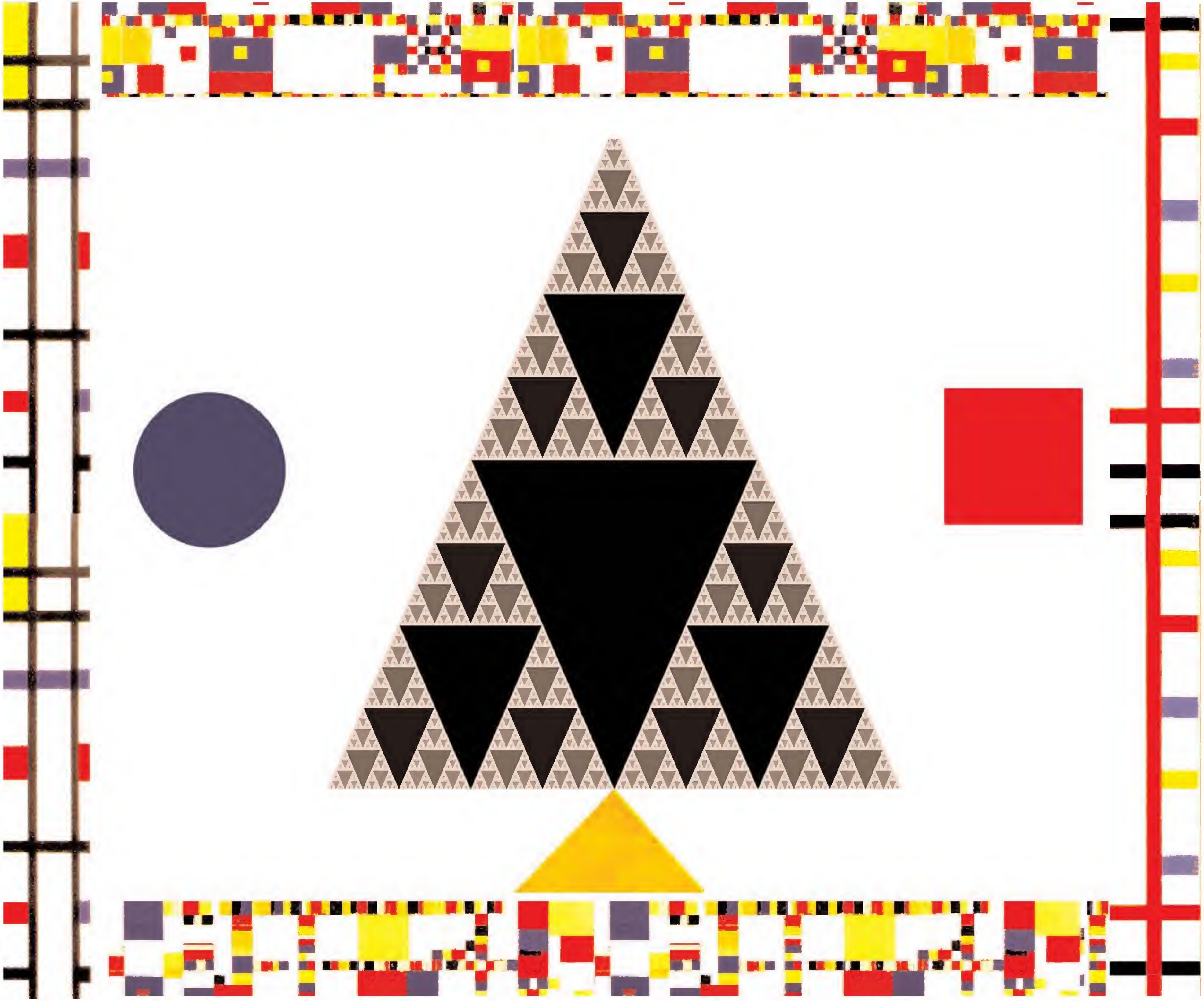
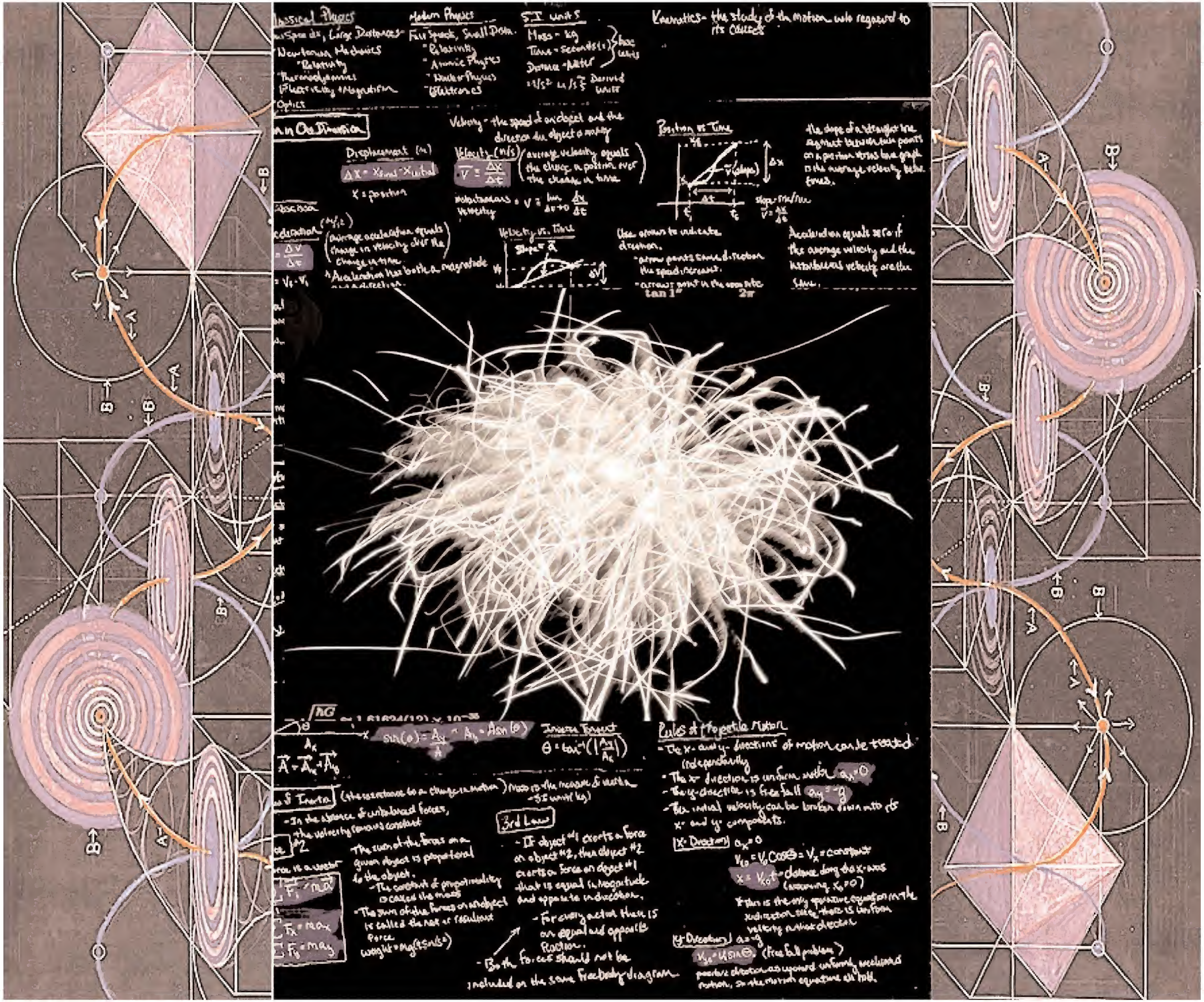


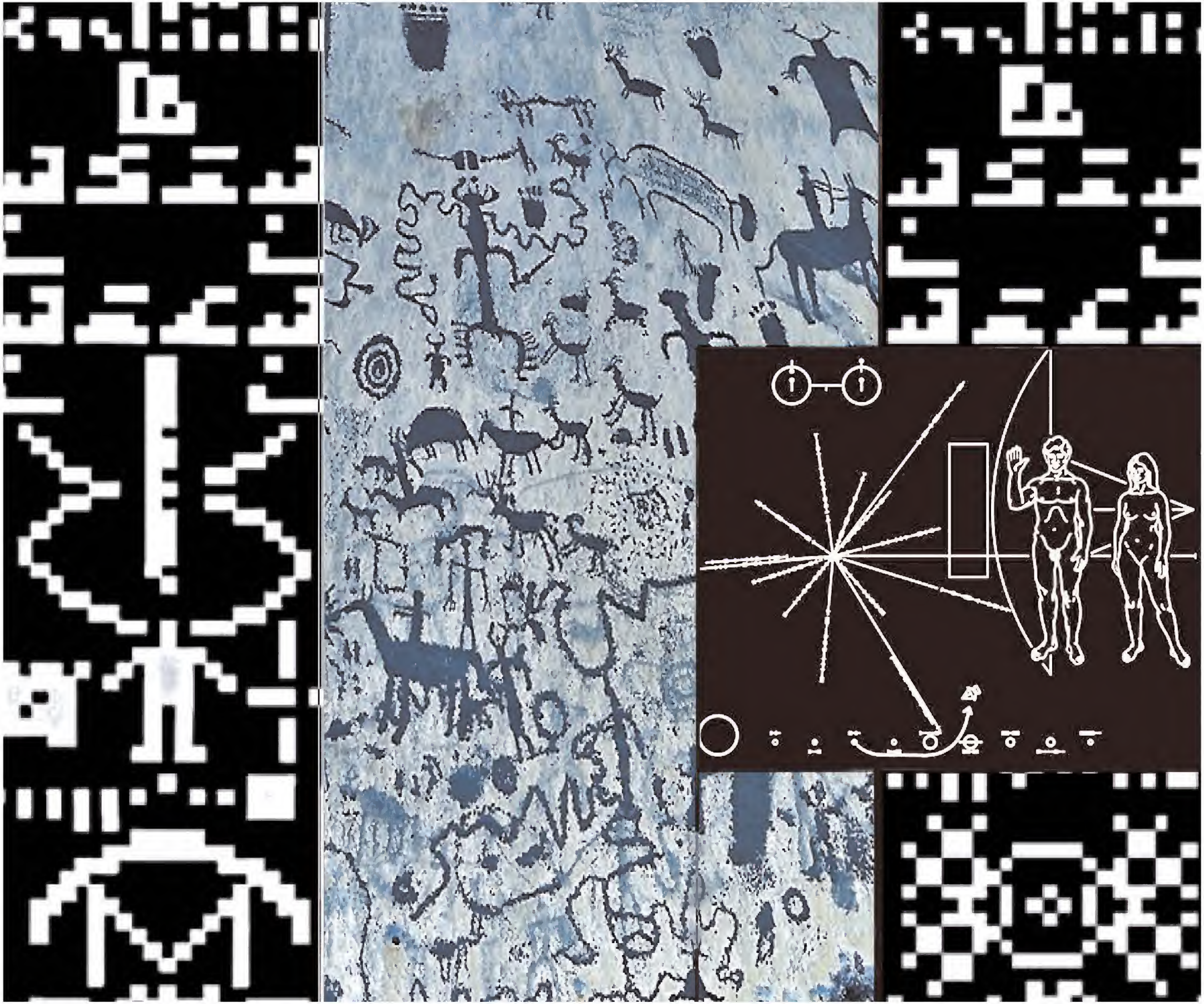


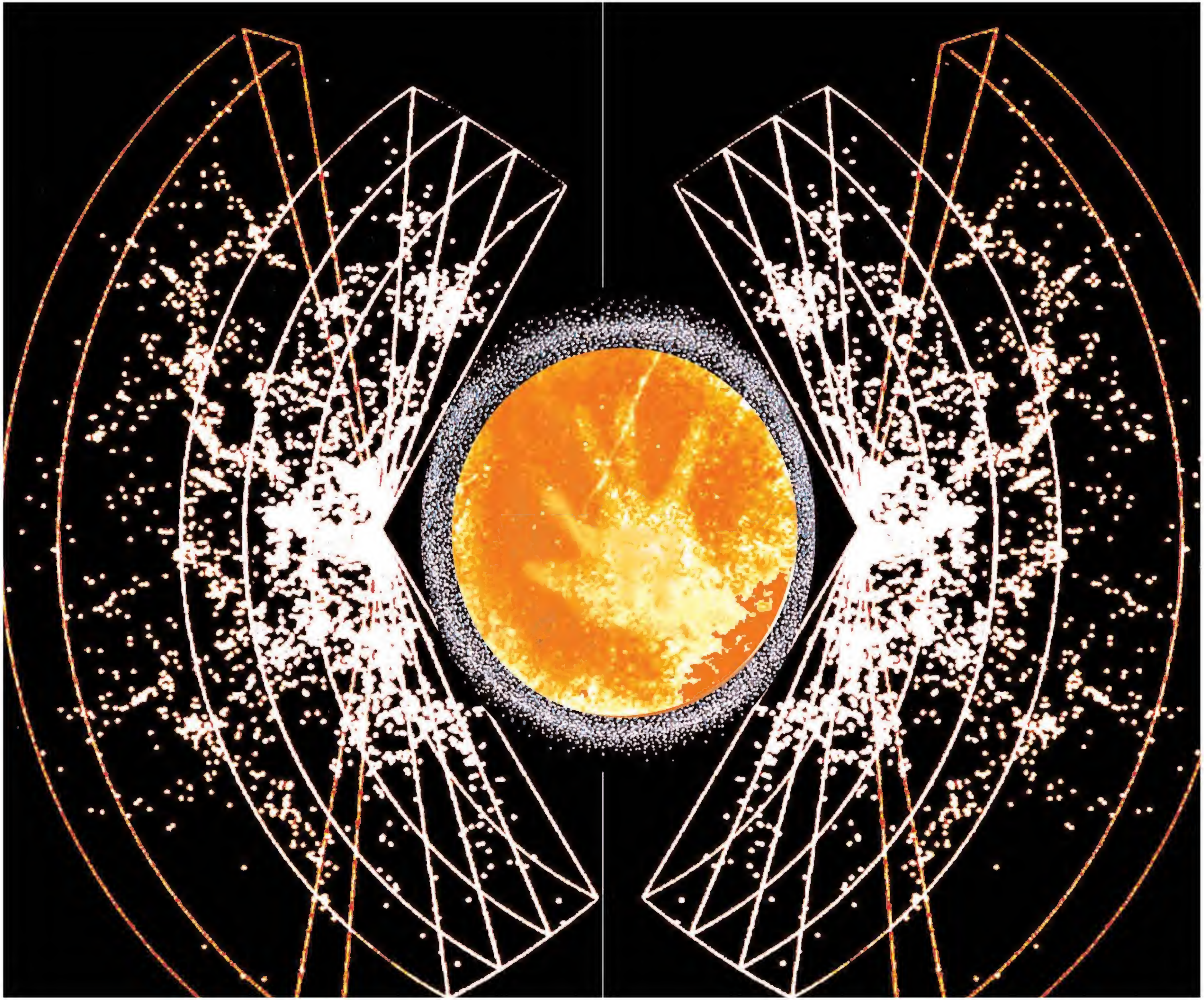


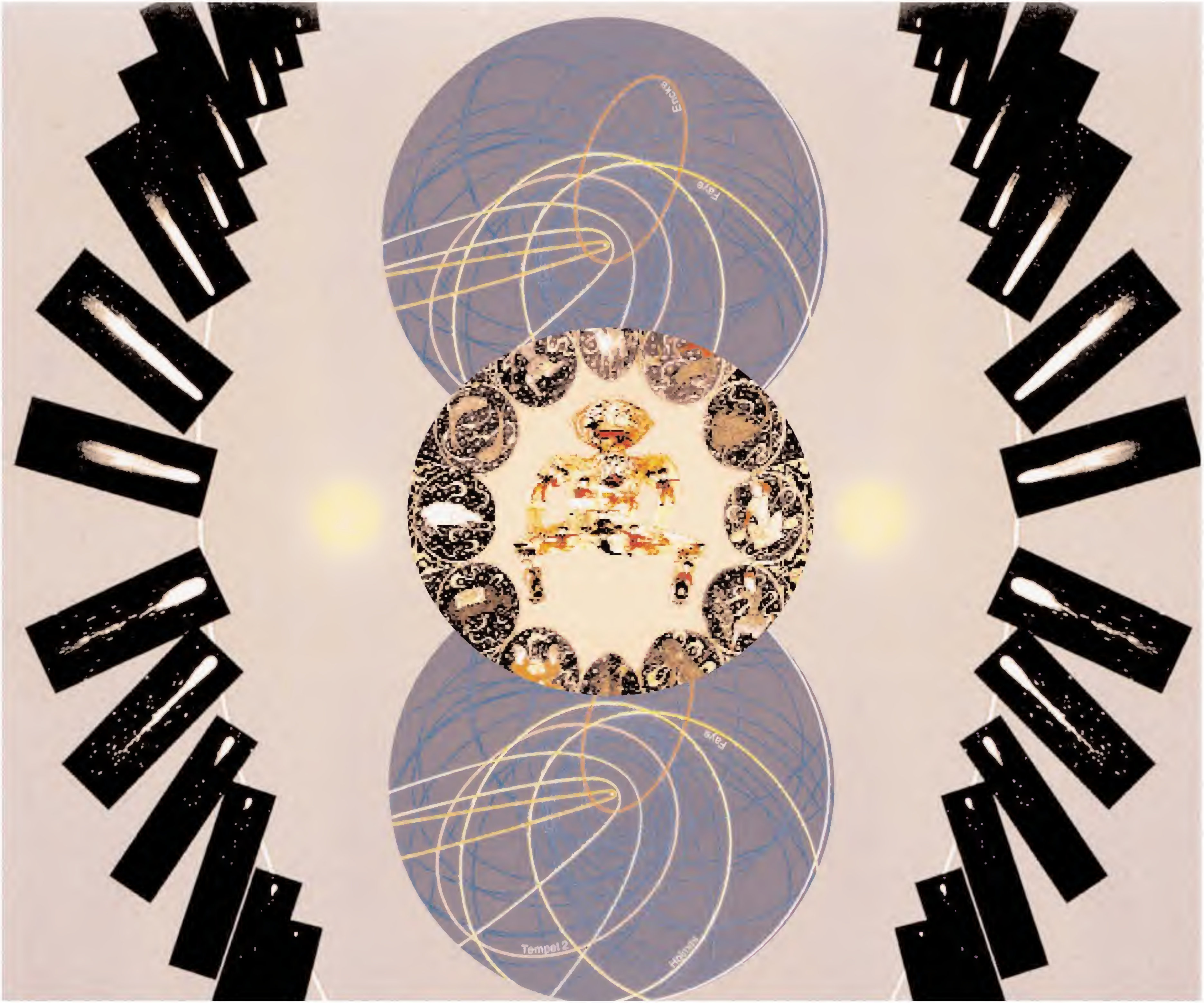




Modern Physics
S.I units
Mass - kg
Time - seconds (s)
Derived units
Kinematics - the study of the motion w/o regard to its causes
Optics
Displacement (m)
x = position
Velocity - the speed of an object and the direction the object is moving
Position vs Time
Velocity vs. Time
Use arrows to indicate direction.
Acceleration equals zero if the average velocity and the instantaneous velocity are the same.
Inverse Tangent
Rules of Projectile Motion
3rd Law
- For every action there is an equal and opposite reaction.
- Both forces should not be included on the same freebody diagram



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